

# Scheduling Scientific Experiments on the Rosetta/Philae Mission

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CP 2012

LAAS-CNRS  
Toulouse, France

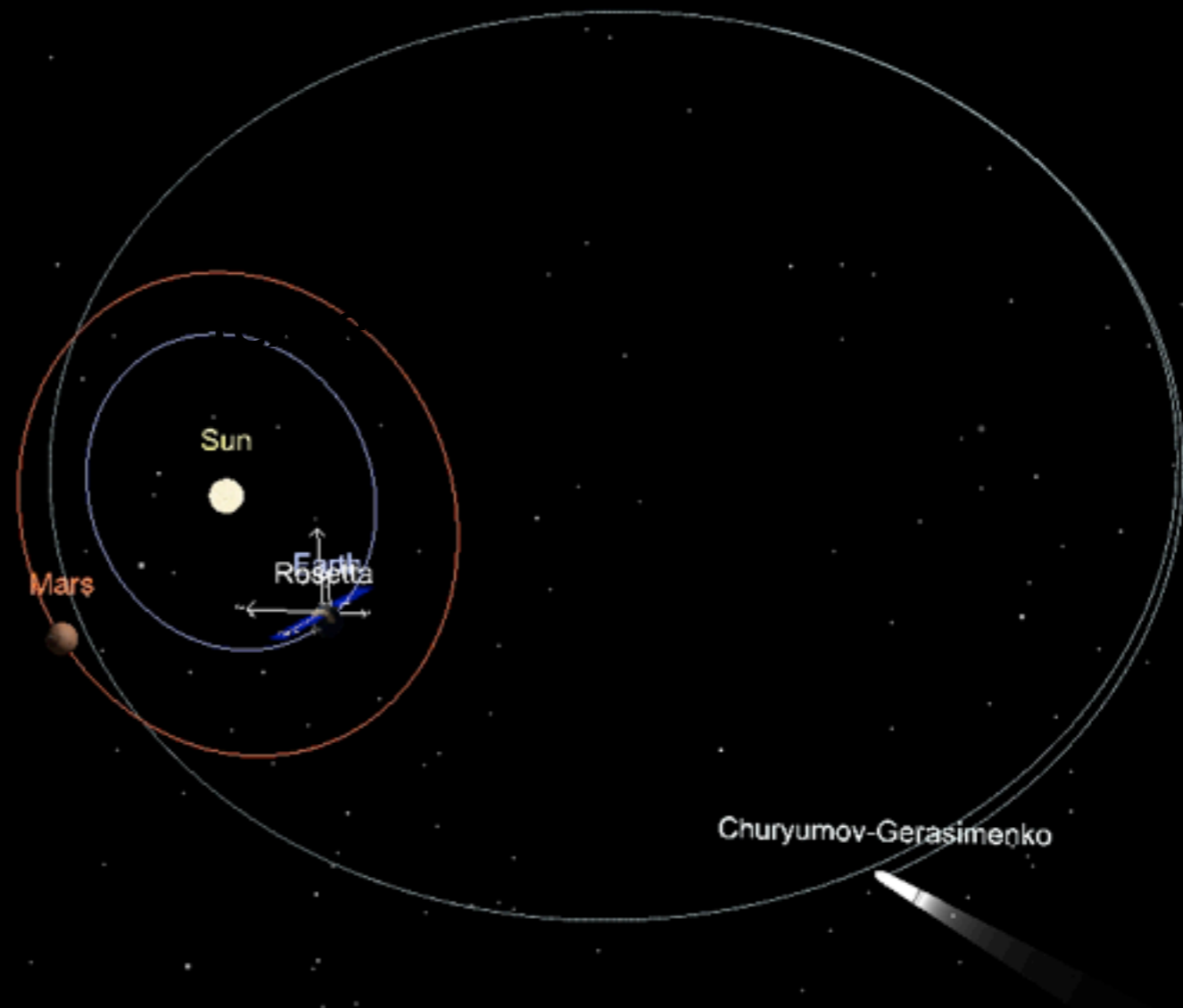
09/10/2012



## ROSETTA-PHILAE



Spacecraft Rosetta

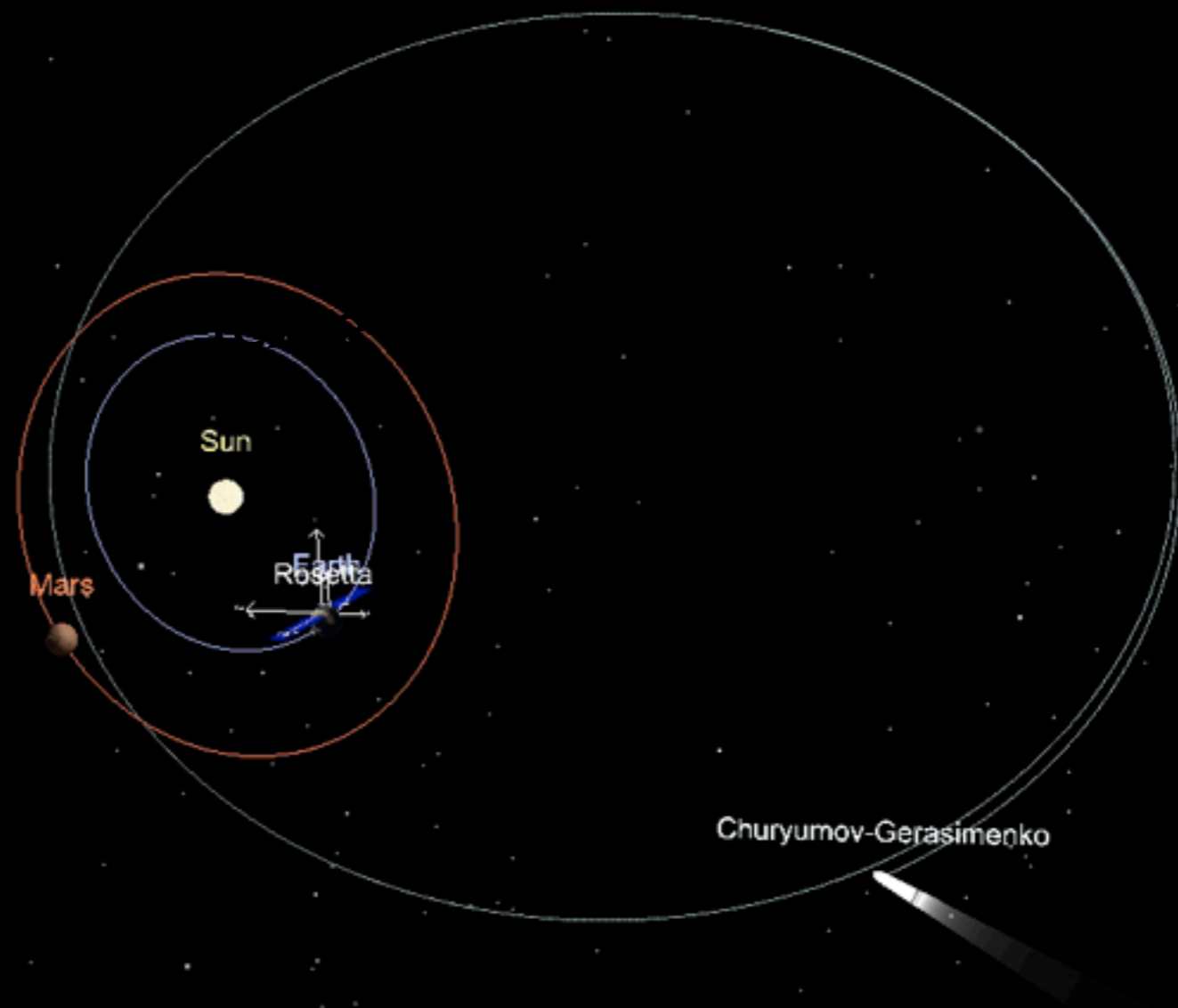


## ROSETTA-PHILAE



Spacecraft Rosetta

ESA/CNES mission  
Sent by Ariane 5 on 2004

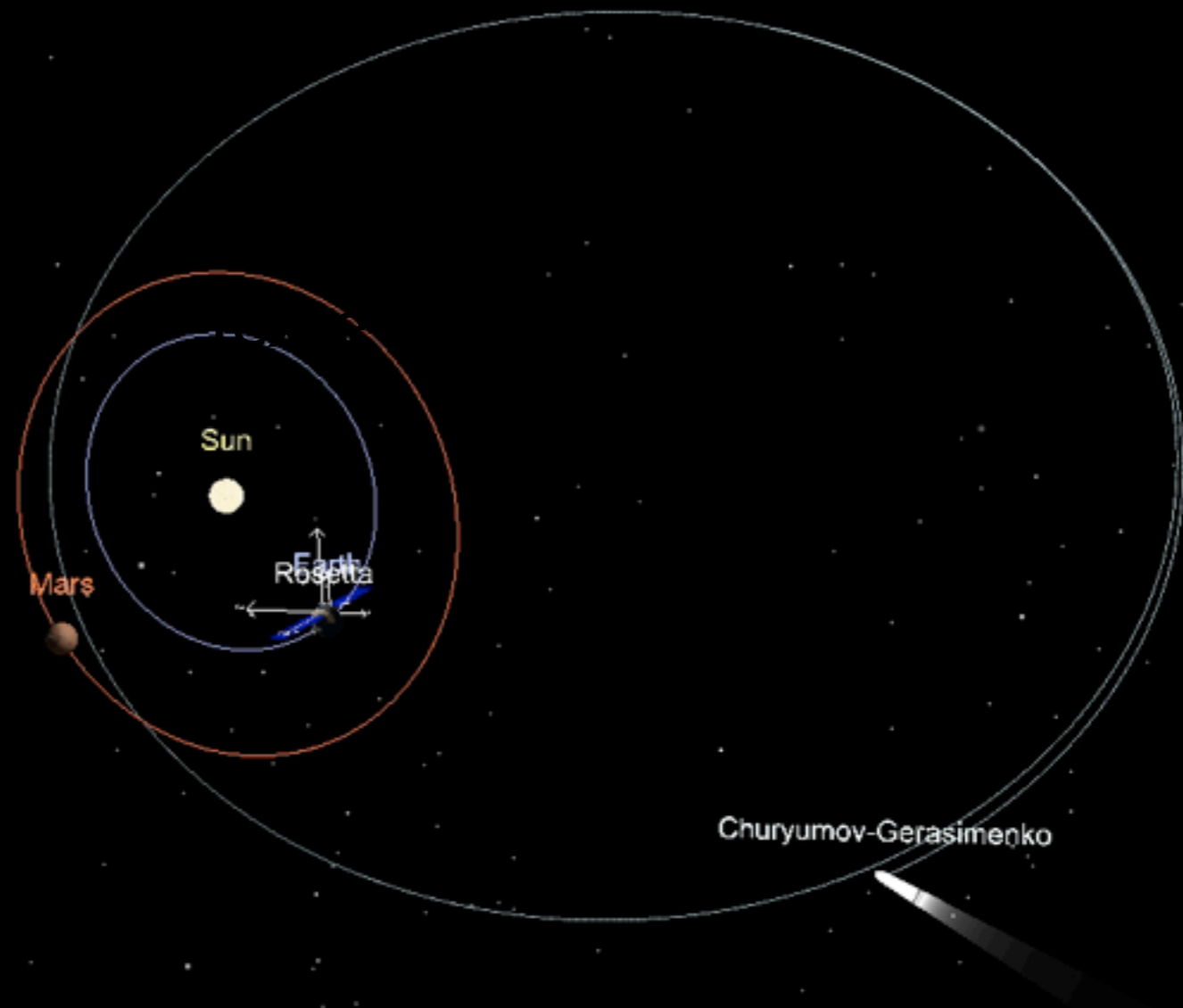


## ROSETTA-PHILAE



Spacecraft Rosetta

Objective (2014):  
Land on a comet  
Analyze its surface



## ROSETTA-PHILAE

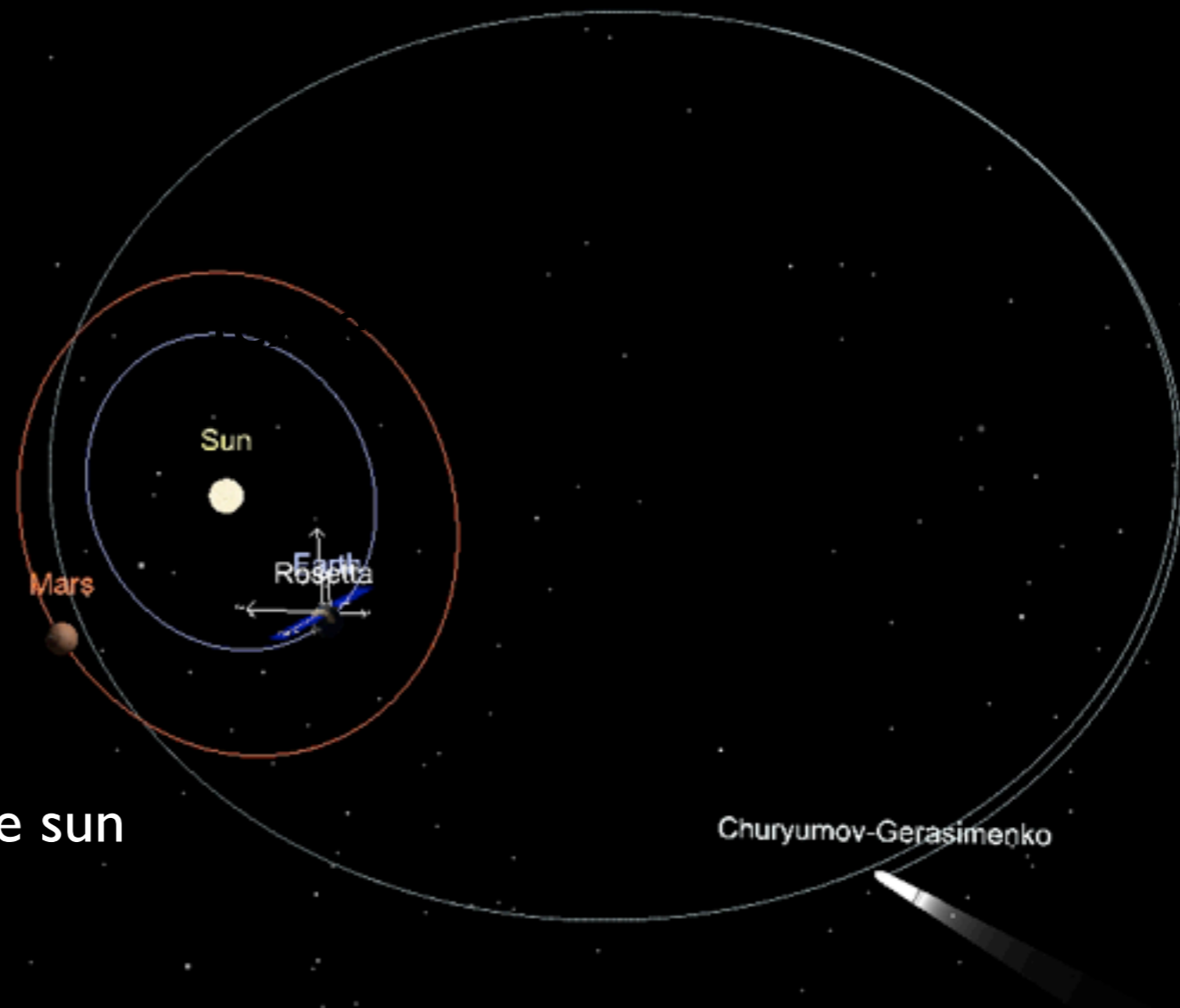


Spacecraft Rosetta

### Trajectory:

4 gravitational accelerations

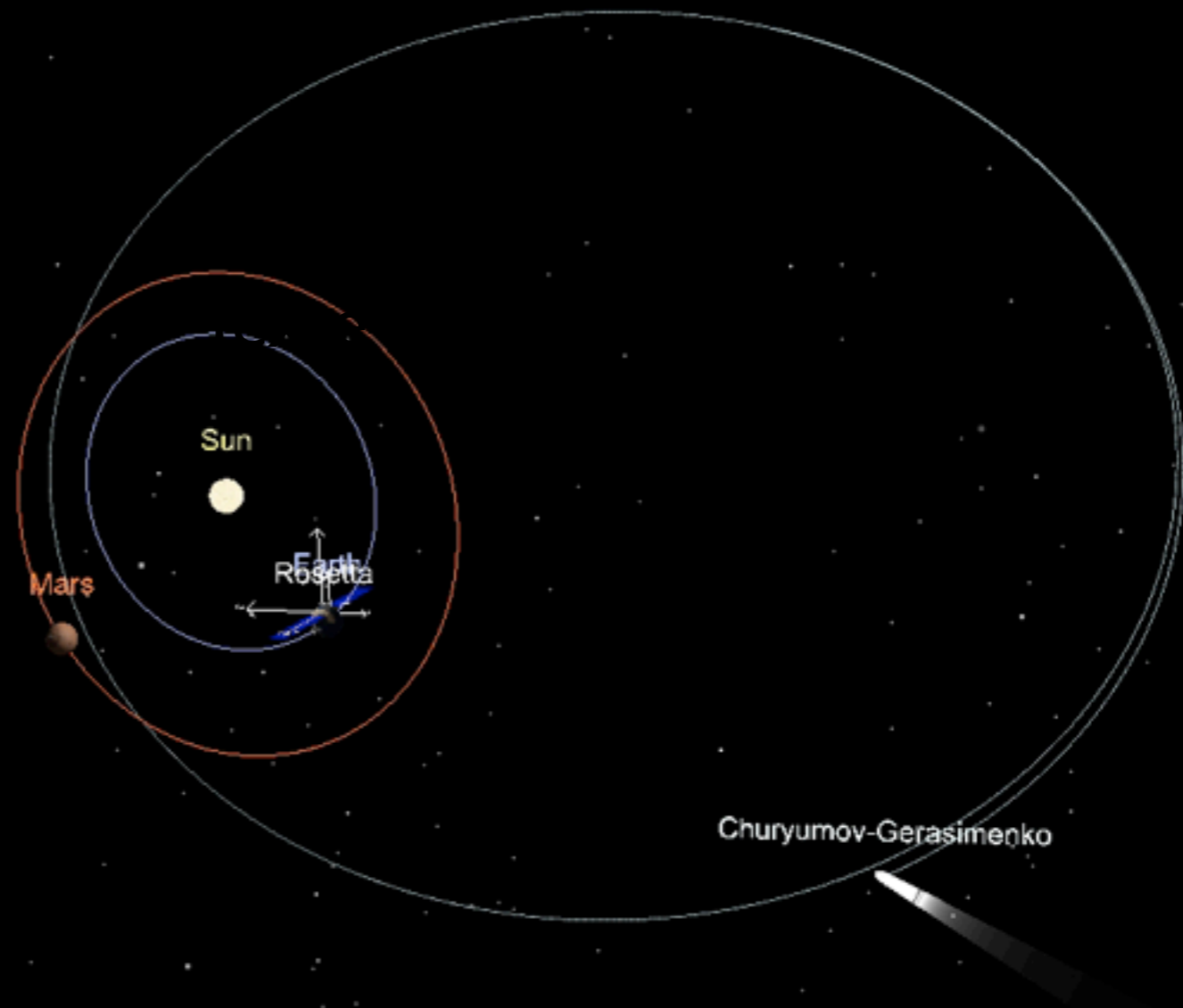
Intercept the comet far from the sun



## ROSETTA-PHILAE



Spacecraft Rosetta



The comet:

Churyumov-Gerasimenko

Mass of ice and snow powder

Limited knowledge

Get information from the past



# ROSETTA-PHILAE

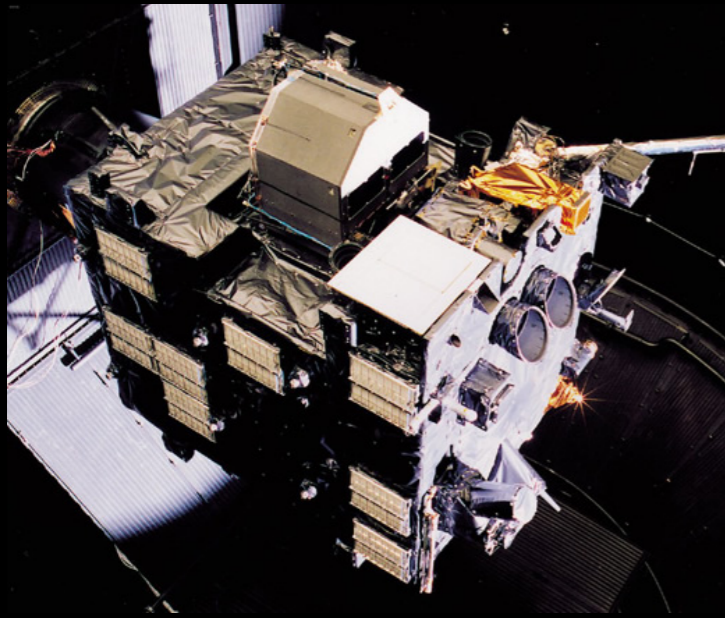


Spacecraft Rosetta

# ROSETTA-PHILAE



Spacecraft Rosetta



Lander Philae

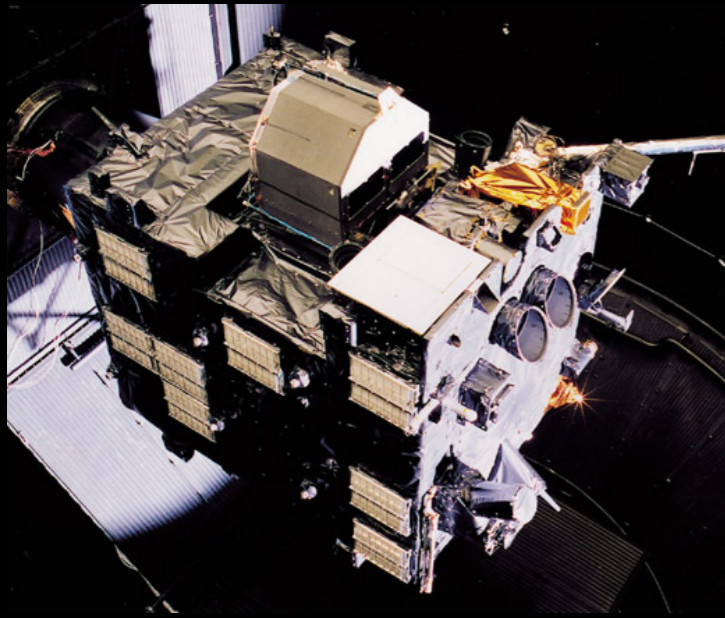
Rosetta stays in orbit and deploys Philae



# ROSETTA-PHILAE



Spacecraft Rosetta



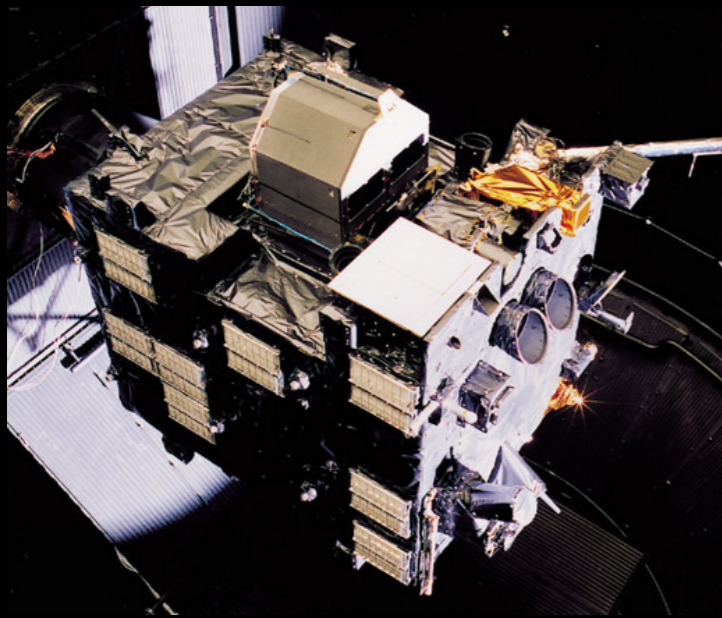
Lander Philae

Rosetta stays in orbit and deploys Philae  
3 phases of experimentation:  
SDL (Separation - Descent - Landing)  
FSS (First Science Sequence)  
LTS (Long Term Science)

# ROSETTA-PHILAE



Spacecraft Rosetta



Lander Philae

## Instruments:

Civa  
Sd2  
Consert  
Romap  
Ptolémé  
Cosac  
Apxs  
Sesame  
Mupus

Rosetta stays in orbit and deploys Philae

3 phases of experimentation:

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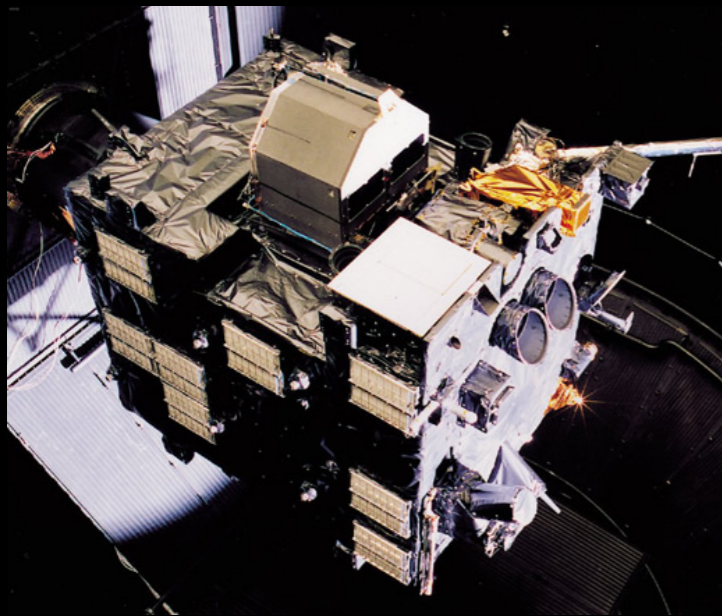
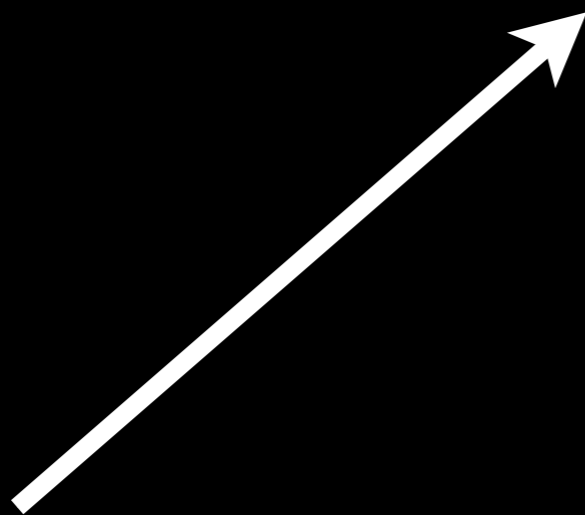
FSS (First Science Sequence)

LTS (Long Term Science)

# ROSETTA-PHILAE



Spacecraft Rosetta



Lander Philae

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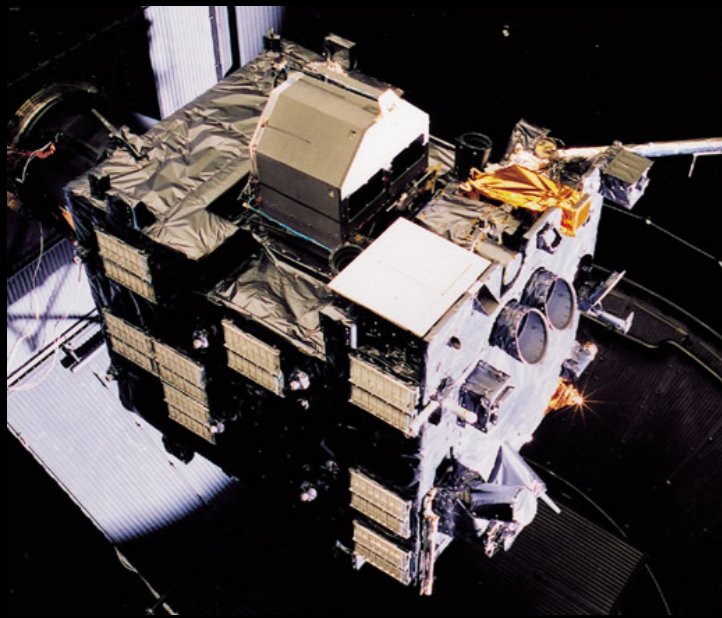
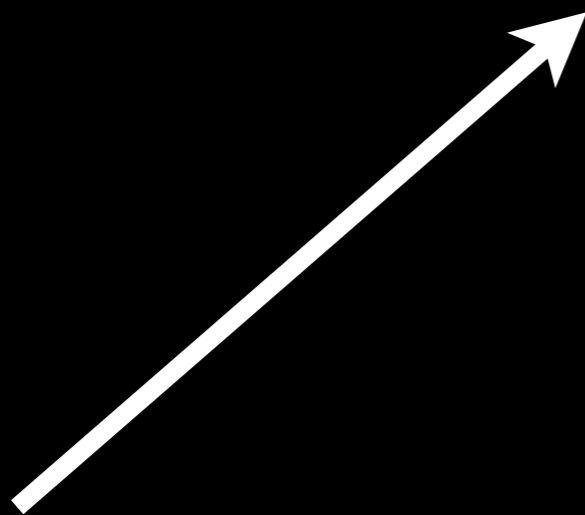
- Civa
- Sd2
- Consert
- Romapi
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- Sesame
- Mupus

- Transfers Experiment memory to Mass Memory
- Transfers Lander to Orbiter
- Transfers Orbiter to Earth

# ROSETTA-PHILAE



Spacecraft Rosetta



Lander Philae

## Instruments:

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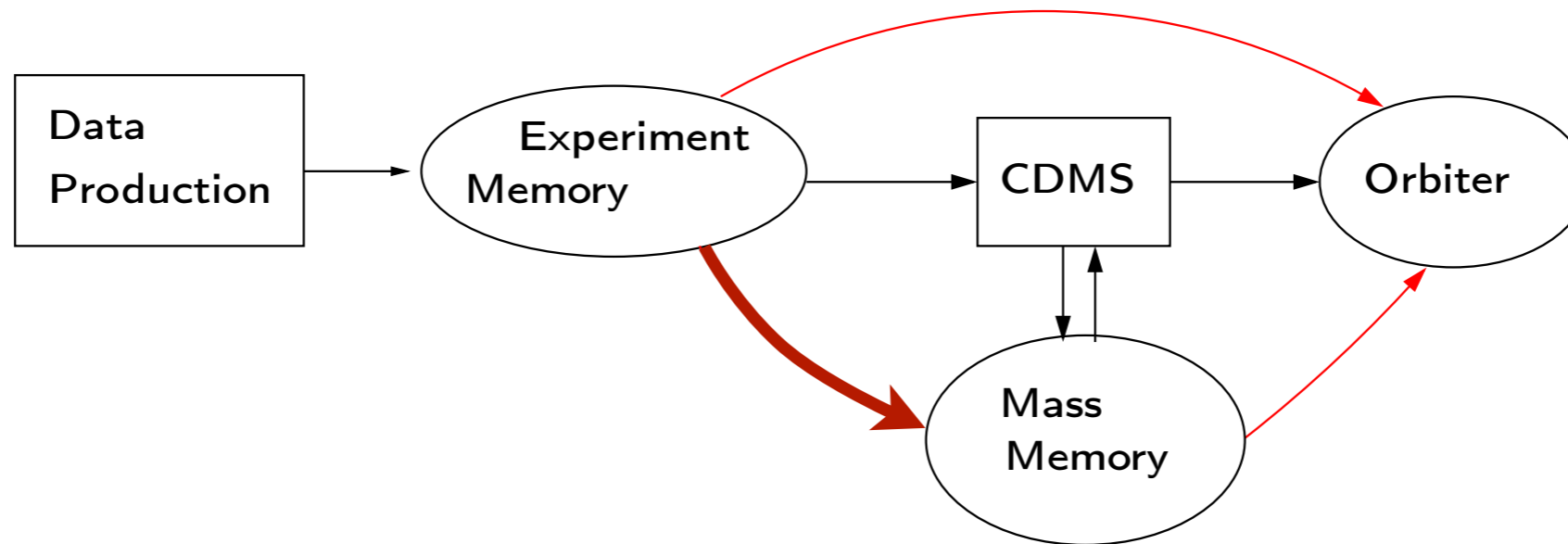
## Constraints:

- Energy
- Limited memories
- Limited transfers to Orbiter

# Outline

- 1 Problem
  - Data Transfer
- 2 Mathematical modeling of transfers
  - A Simplified model of Data Transfer
- 3 Algorithms
  - Sweep Algorithm
  - Filtering algorithms
- 4 Benchmarks

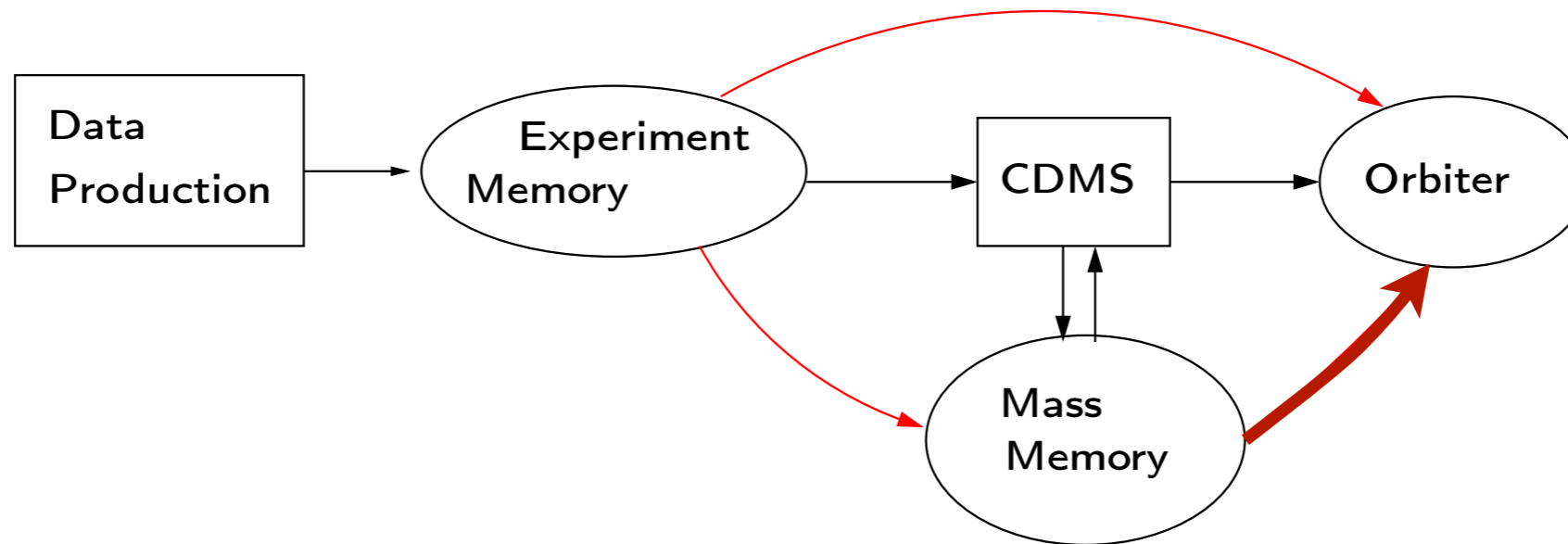
# Data transfer problem



## Data flow

- Experiments produce data and store it into their own memories
- The CDMS manages data transfers (following a fixed policy)
  - Transfer data from an experiment to the mass memory

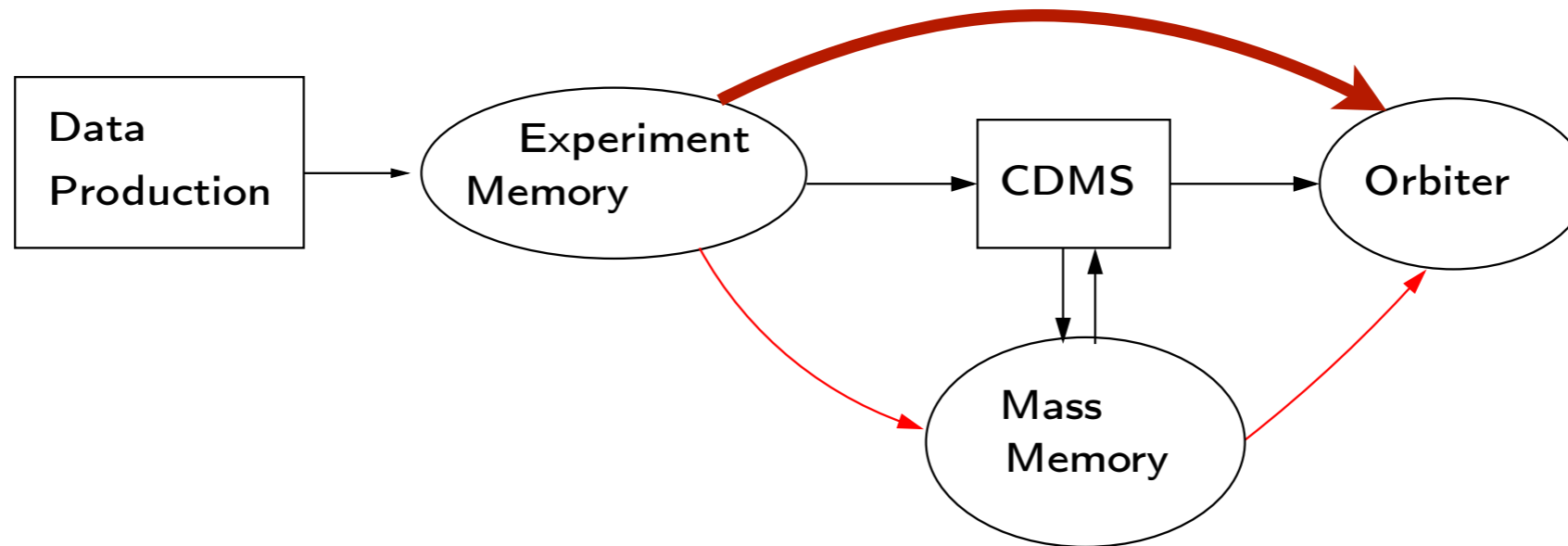
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# Data transfer problem

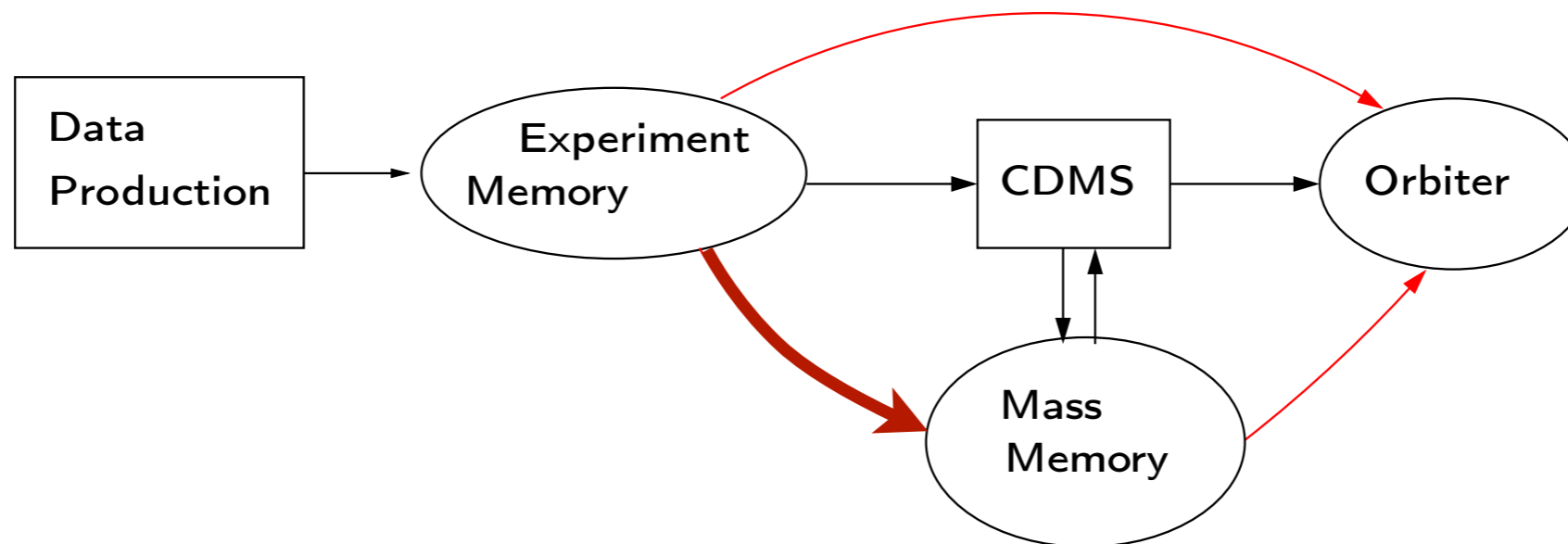


## Data flow

- Experiments produce data and store it into their own memories
- The CDMS manages data transfers (following a fixed policy)
  - Transfer data from an experiment to the mass memory
  - Transfer data from the mass memory to the orbiter
  - Transfer data from an experiment directly to the orbiter



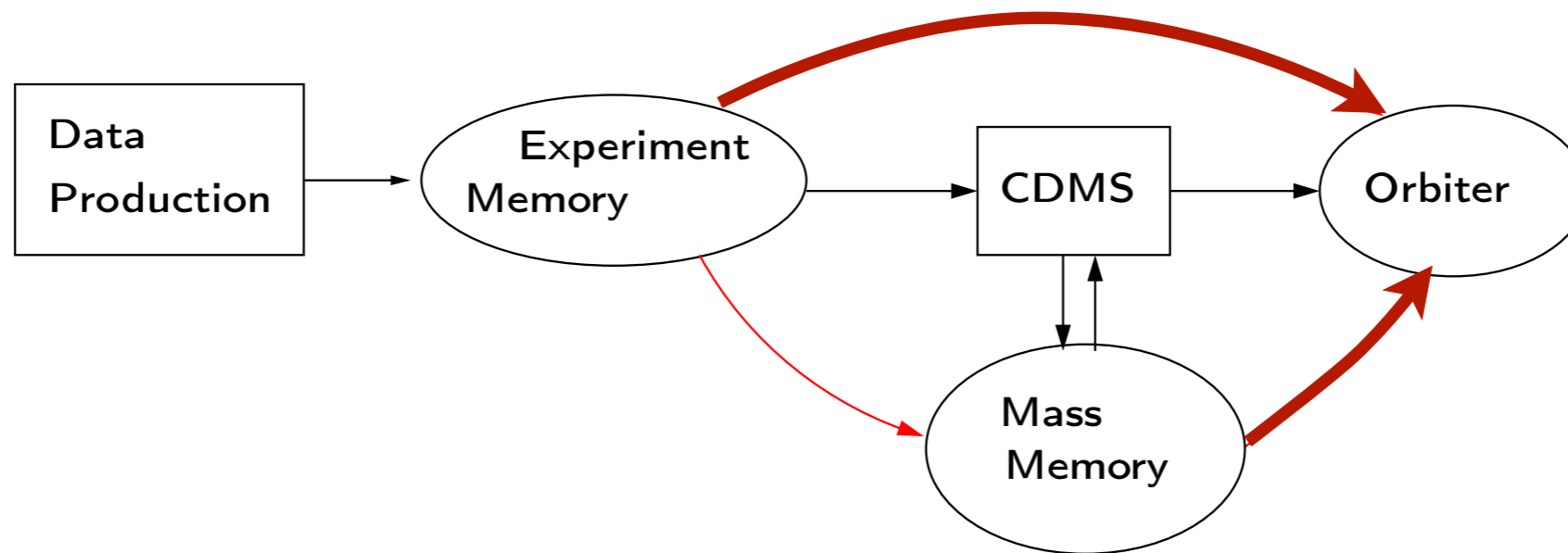
# CDMS - Command and Data Management System



## Transfers to the mass memory

- Repeat *as long as the mass-memory is not full*:
  - Scan experiments by decreasing priority
  - Stop at the first experiment holding some data
  - Transfer one block of data from this experiment to the mass memory

# CDMS - Command and Data Management System



## Transfers to the orbiter

- When Rosetta is *visible* (over the horizon):
  - If the mass memory is empty: do as above, but directly to the orbiter
  - Otherwise, do as above *and* transfer data from the mass memory to the orbiter

## Data loss

- The CDMS policy may lead to *data loss*
  - When an experiment of low priority produces too much data too quickly
  - When the mass memory is full and the orbiter is not visible

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## How to avoid data loss

- Other than assigning priorities, we have no control on data transfer
- Priorities are fixed for long periods
- One needs to schedule data producing tasks so that those circumstances will not occur
  - Global constraint on data producing tasks

# Previous approach (CNES)

## MOST

- Development of a model/solver tool named **MOST**
- Constraint Programming (with ILOG Scheduler/Solver)

## Model for data transfer

- Modeled with reservoir resources (IloReservoir)
  - Production tasks fill the resources
  - *Predefined transfer tasks (of variable duration) empty the resources*
    - Many extra variables, poor propagation, precision loss

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# Constraint checking - Computing the transfers

## Constraint checking

- We need to compute memory occupation through time
- Once data producing tasks are scheduled, it is possible to “unroll” the policy of the CDMS
  - Costly: we may need as many steps as blocks of data to transfer!

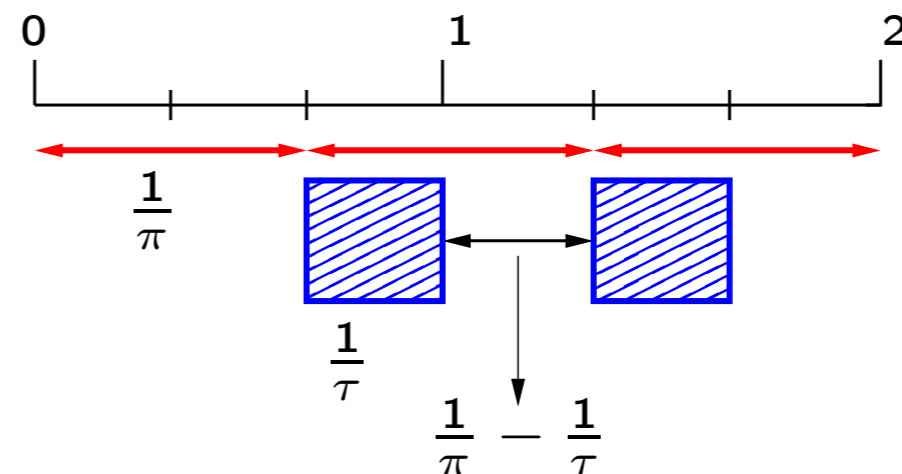
# Constraint checking - Computing the transfers

## Constraint checking

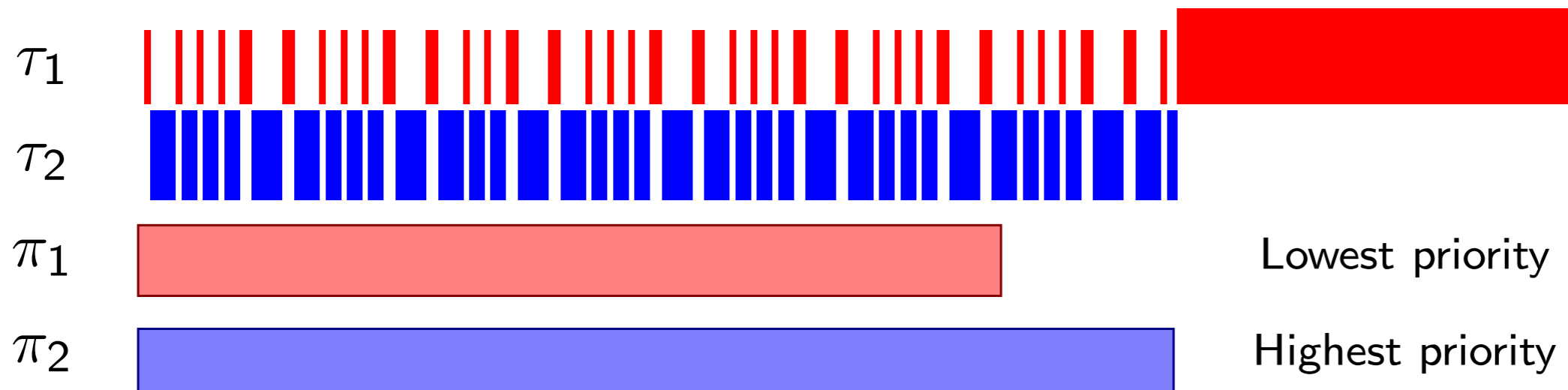
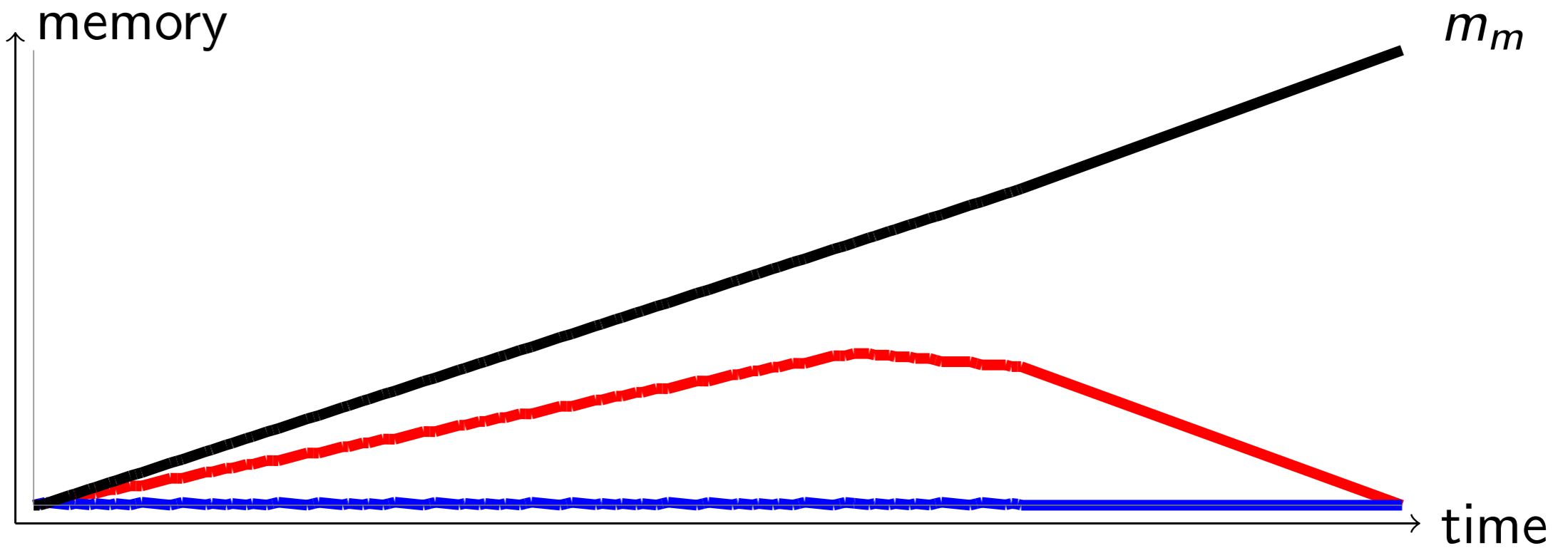
- We need to compute memory occupation through time
- Once data producing tasks are scheduled, it is possible to “unroll” the policy of the CDMS
  - Costly: we may need as many steps as blocks of data to transfer!
  - Let  $\pi$  be the production rate and  $\tau$  the transfer rate
  - If  $\pi < \tau$  there are gaps that can be used for other experiments

Production  $\pi = 1,5 \text{ blk/s}$

Transfer  $\tau = 3 \text{ blk/s}$



# Example with two experiments



Lowest priority

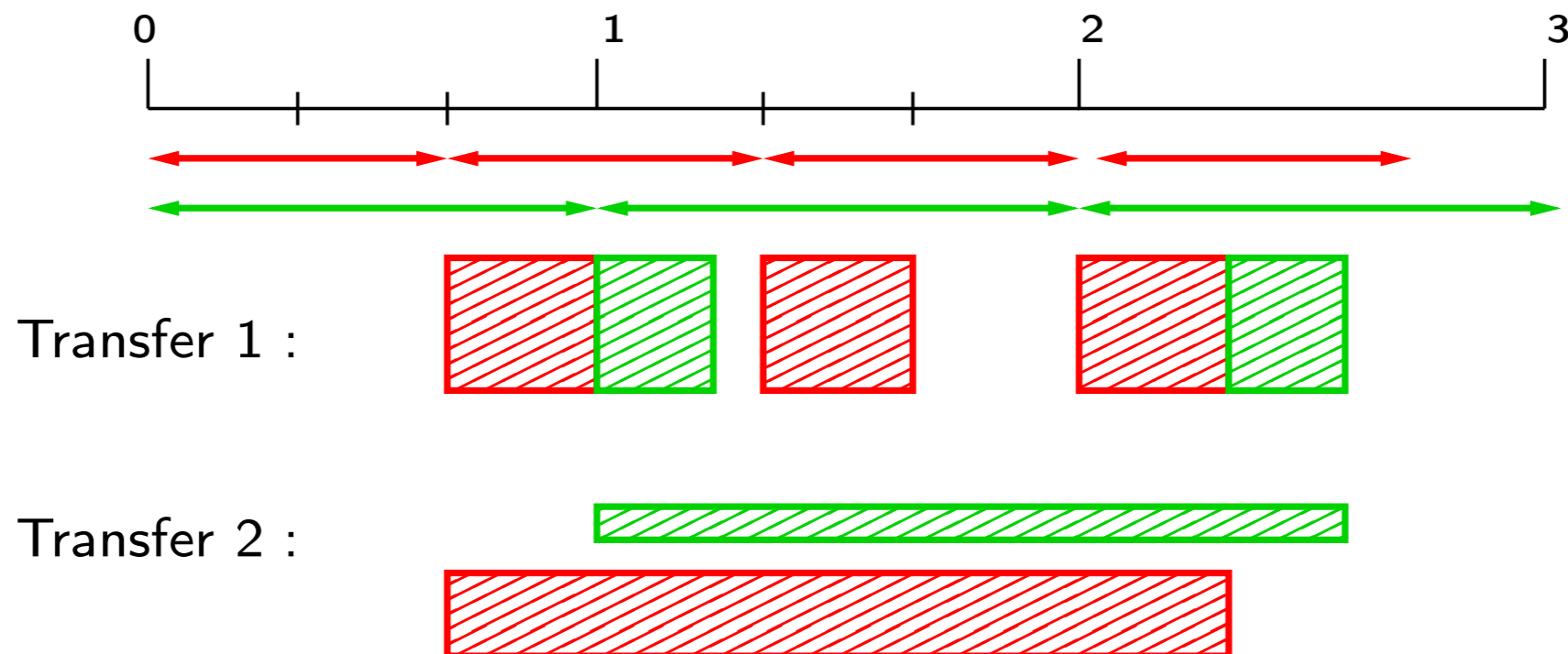
Highest priority

## Modification

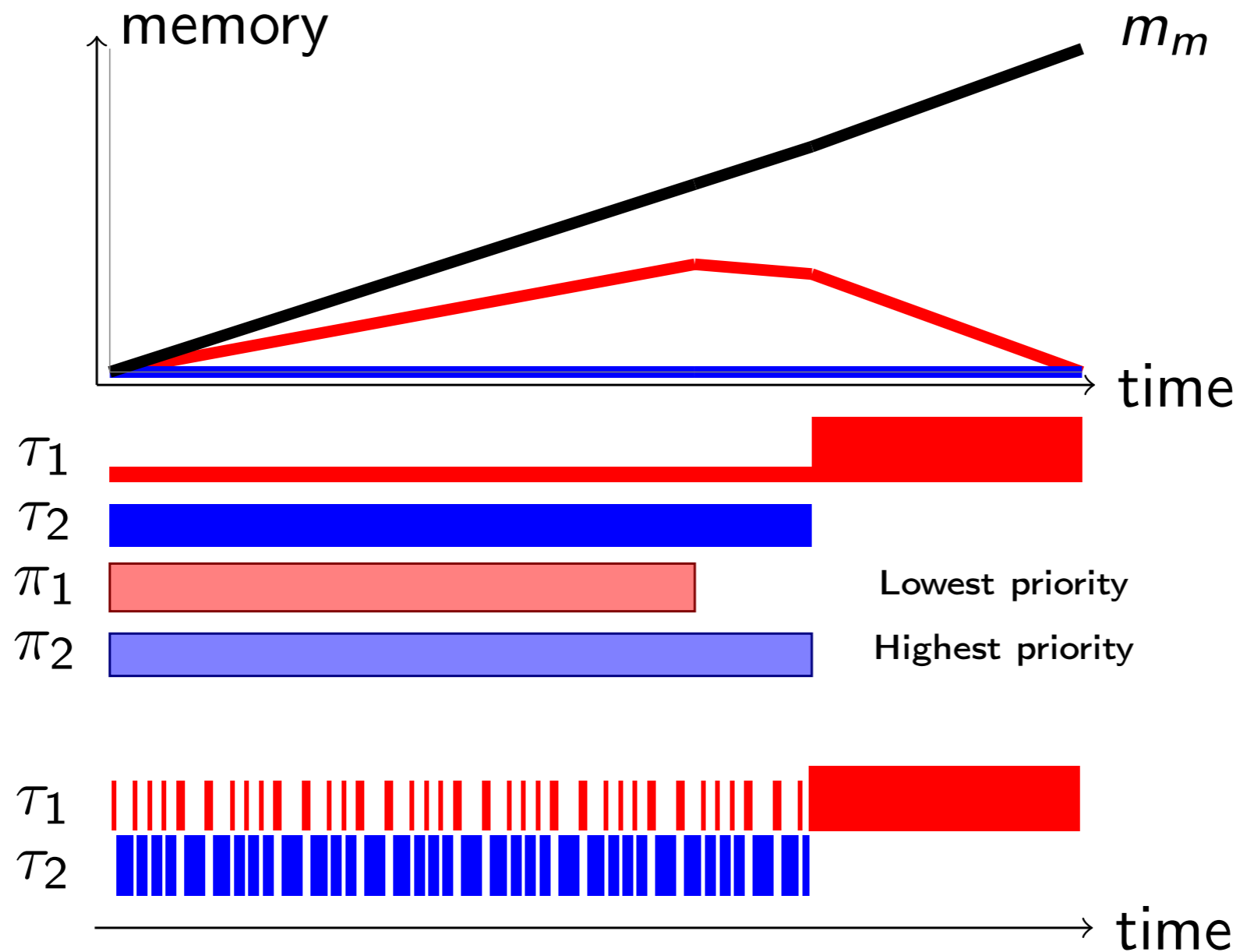
- Approximate switches between experiments by the partition of a *bandwidth*
- The bandwidth is allocated proportionally to the usage of the bus

## Modification

- Approximate switches between experiments by the partition of a *bandwidth*
- The bandwidth is allocated proportionally to the usage of the bus
  - The area (transfer time  $\times$  rate) is equivalent
  - We create only one transfer



# Same example, using the “bandwidth” view



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## For the transfers

- A sweep algorithm to check the constraint
  - Given a schedule of production, the transfers are computed in  $O(n \log n)$



## Principle of the sweep algorithm for computing transfer

- We consider a list of events in a chronological order
  - start/end of an experiment
  - start/end of data production
  - start/end of visibility

## Principle of the sweep algorithm for computing transfer

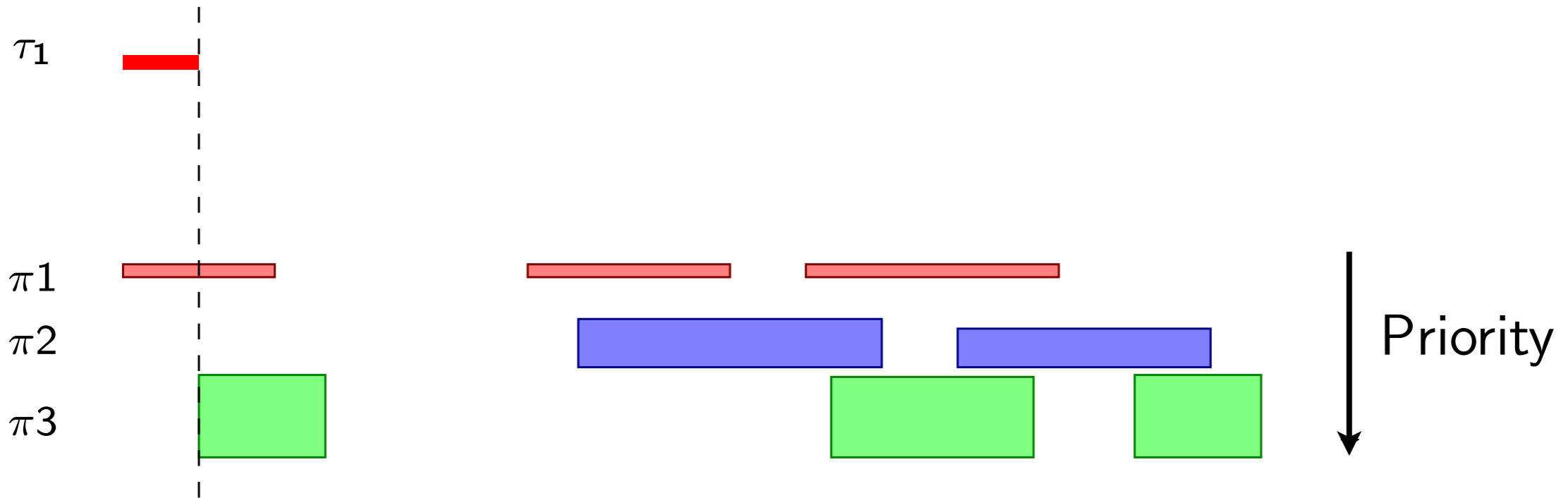
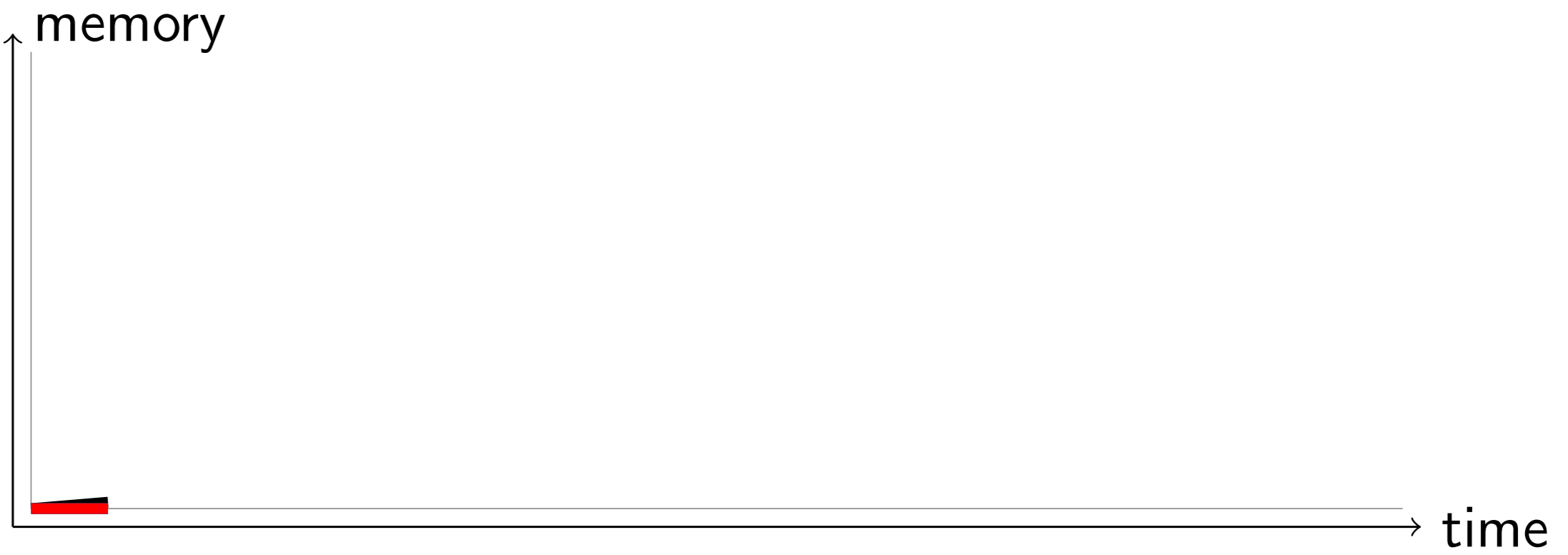
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- At each step, we apply the policy rules of the CDMS (priority) in order to determine the current transfers
  - Nothing will change until the next event
  - If the current transfer empty a memory until the next event, then we create the event "Memory emptied"
  - If the mass memory is full before the next event, we create the event "Full mass memory"

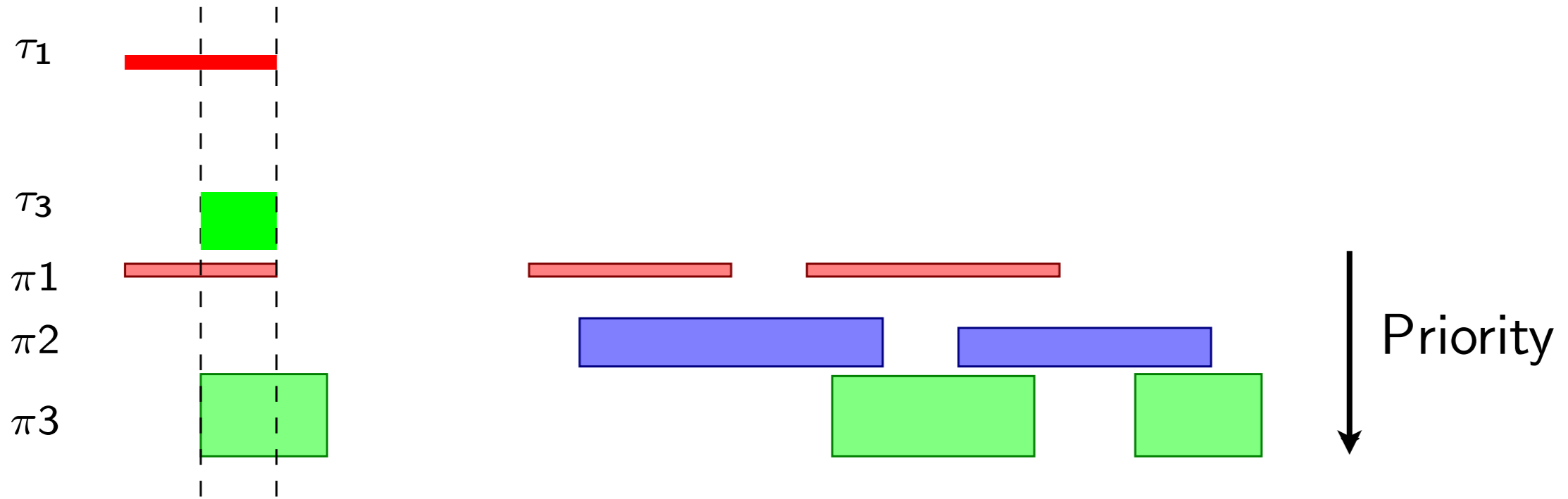
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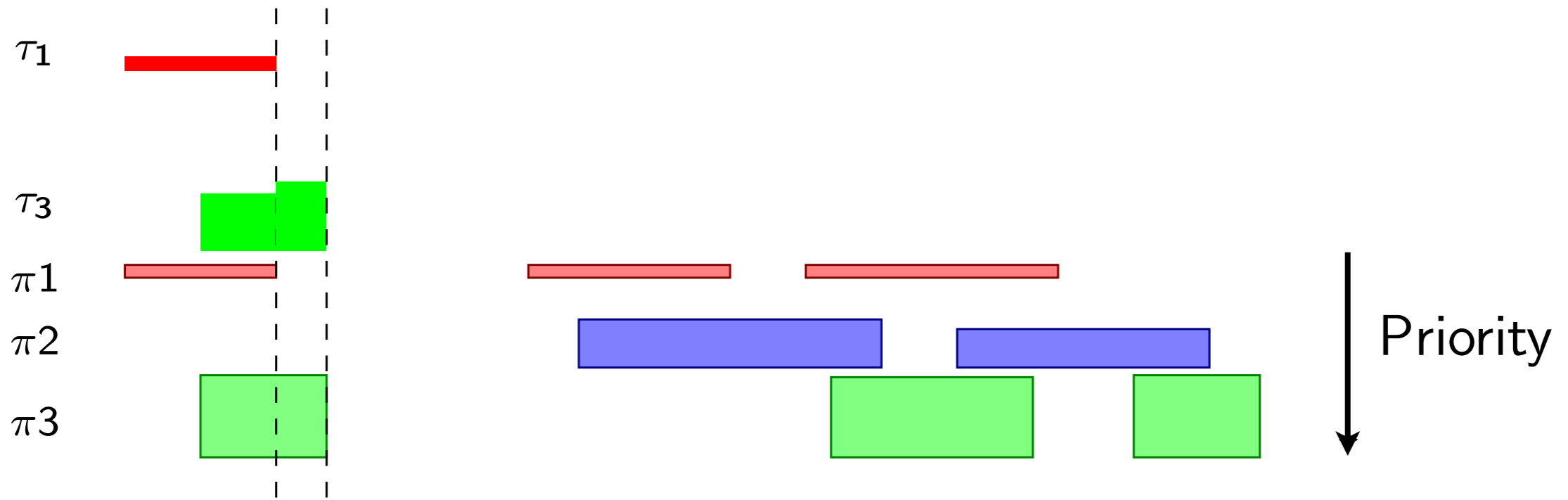
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- If at any time the capacity of an experiment memory is exceeded, then data is lost and the constraint is violated for this schedule.

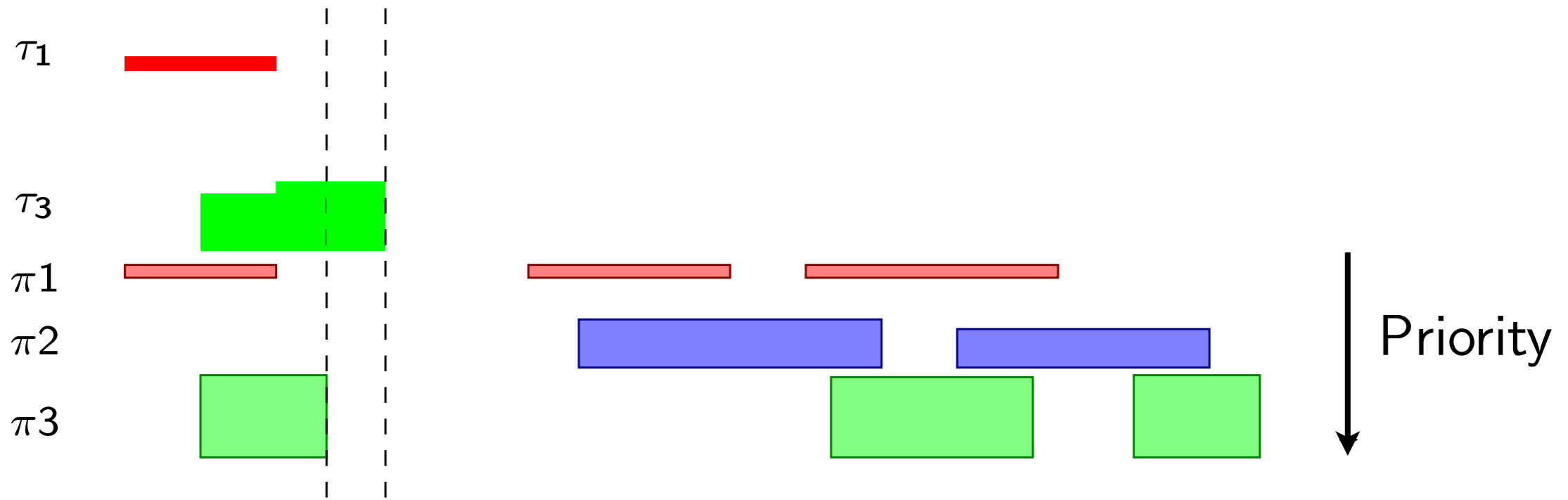
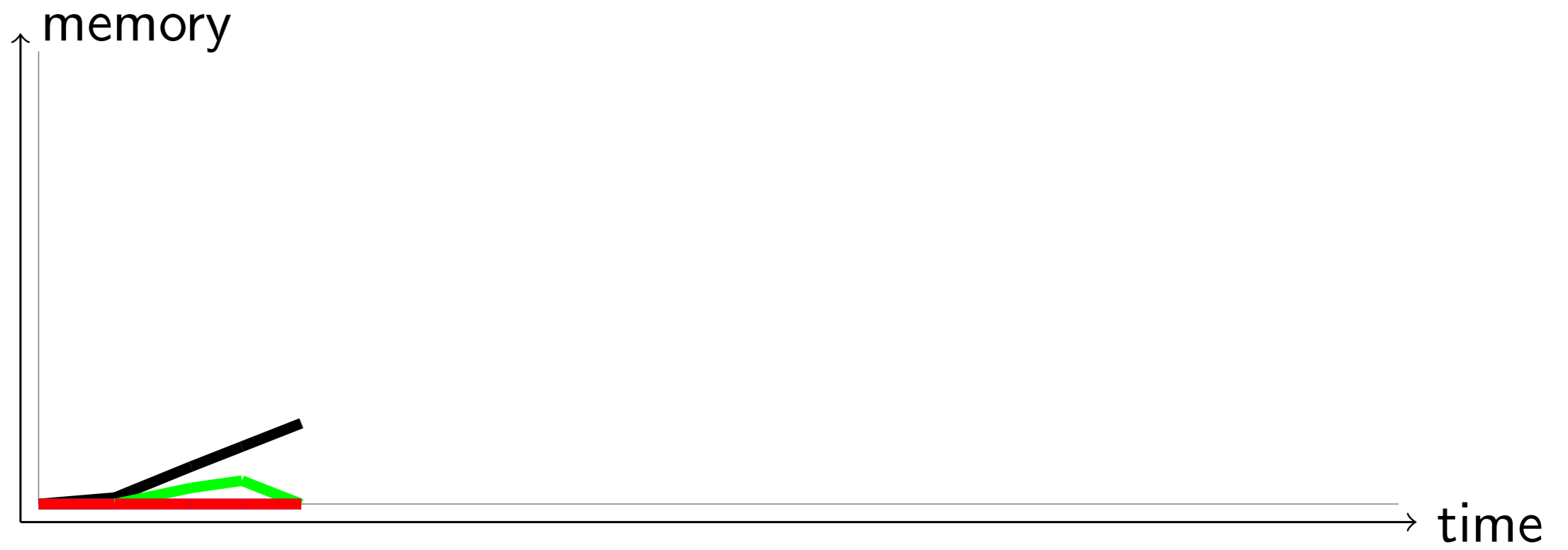
 $\pi_1$  $\pi_2$  $\pi_3$ 

Priority

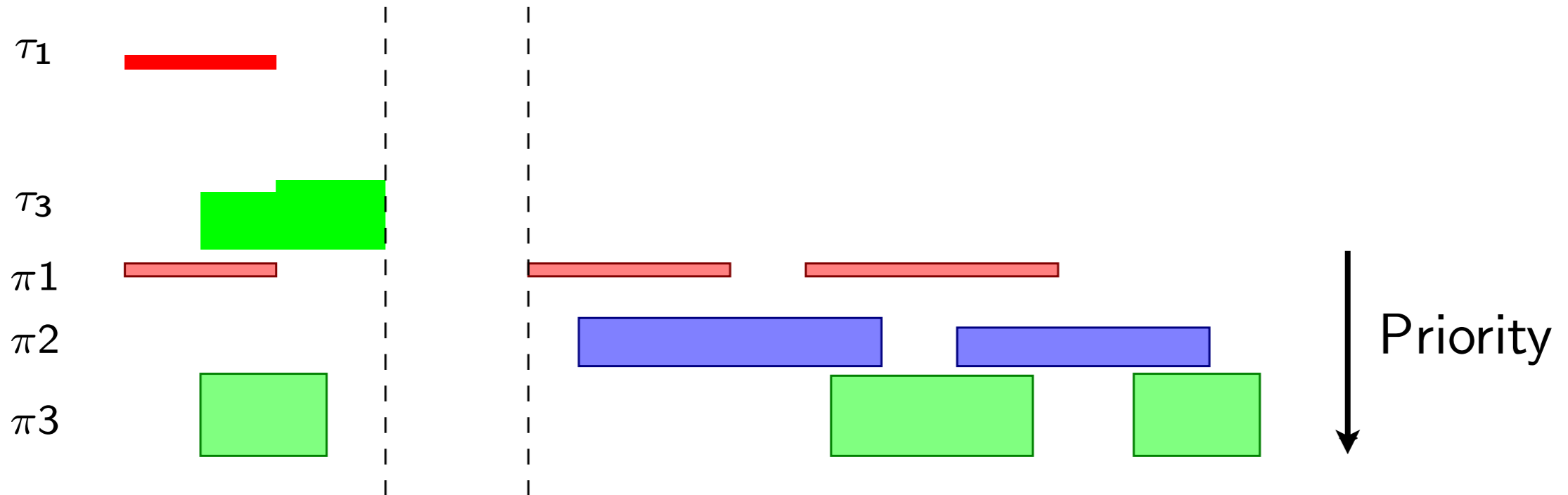


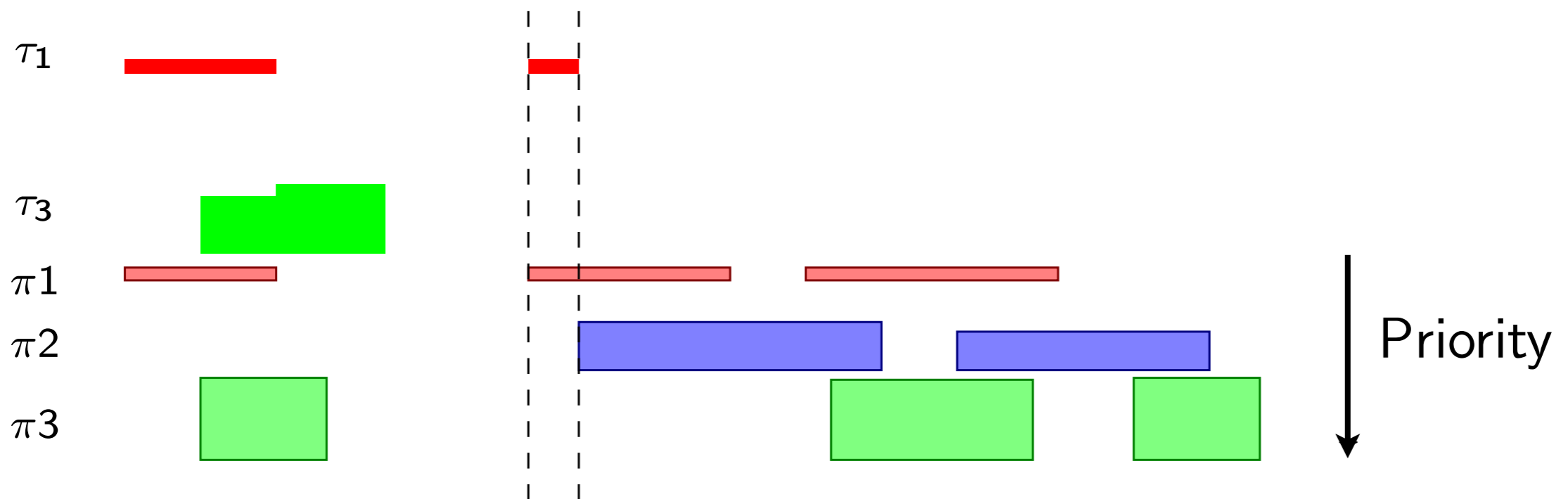


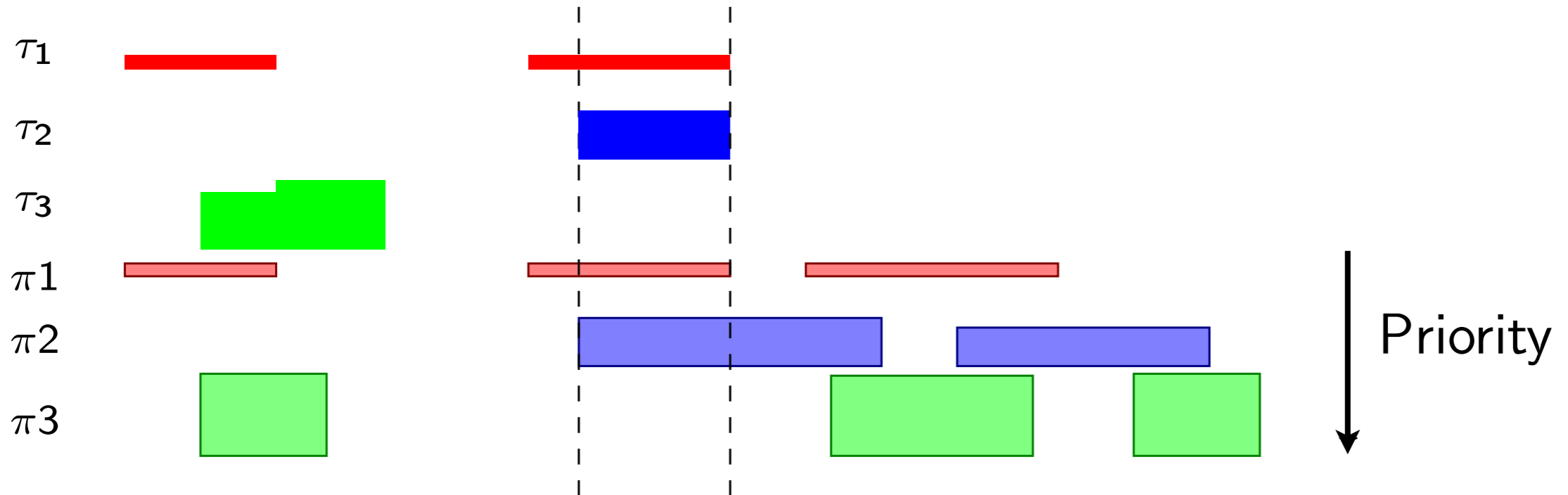
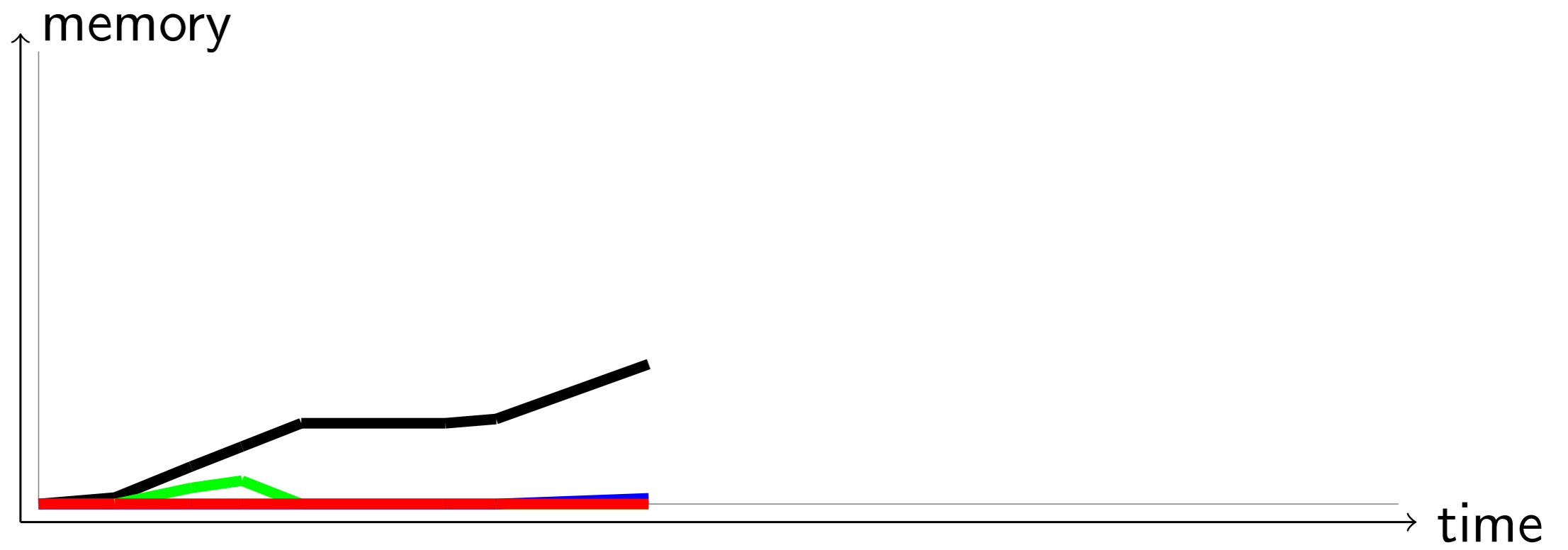


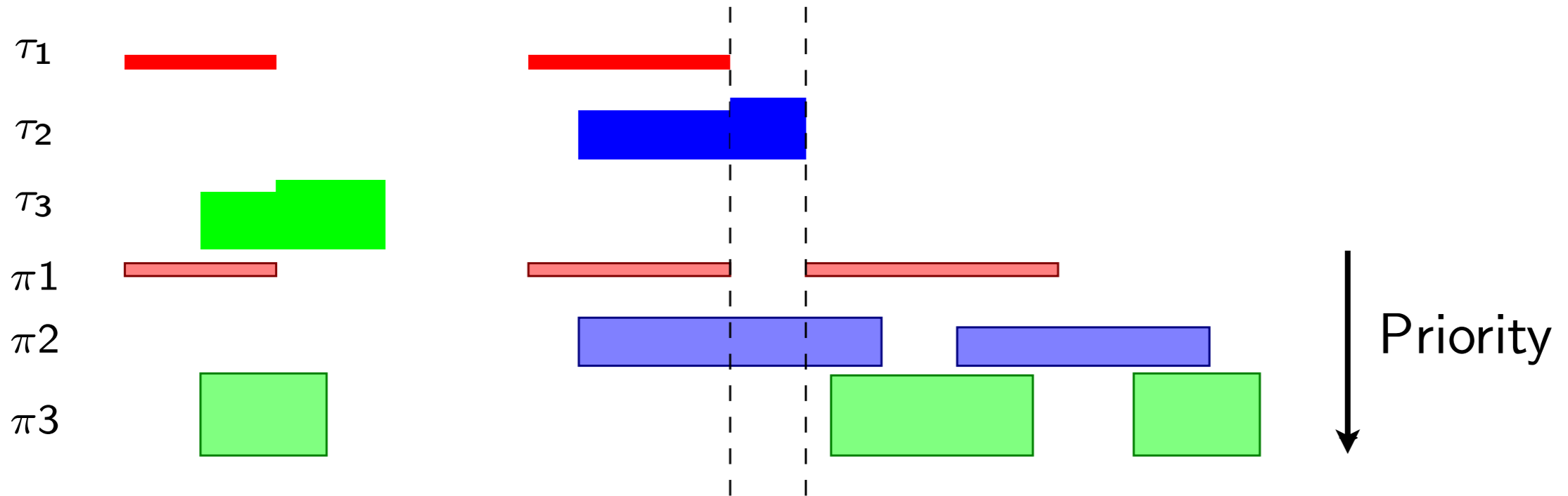
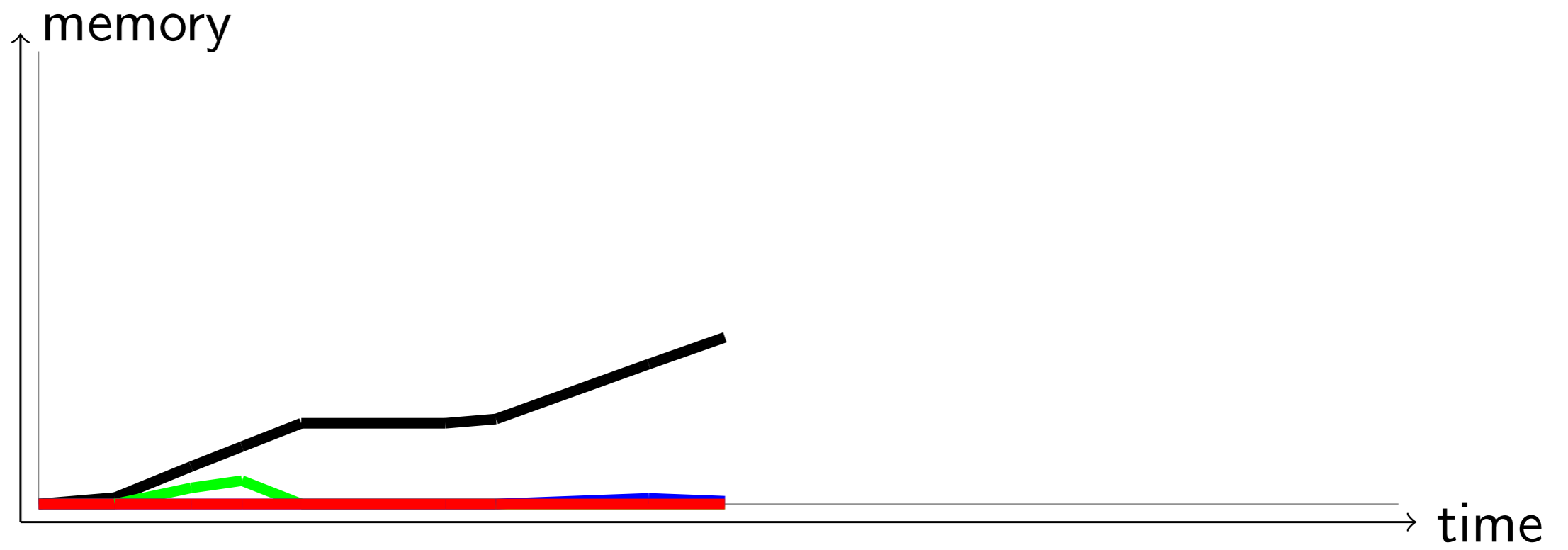


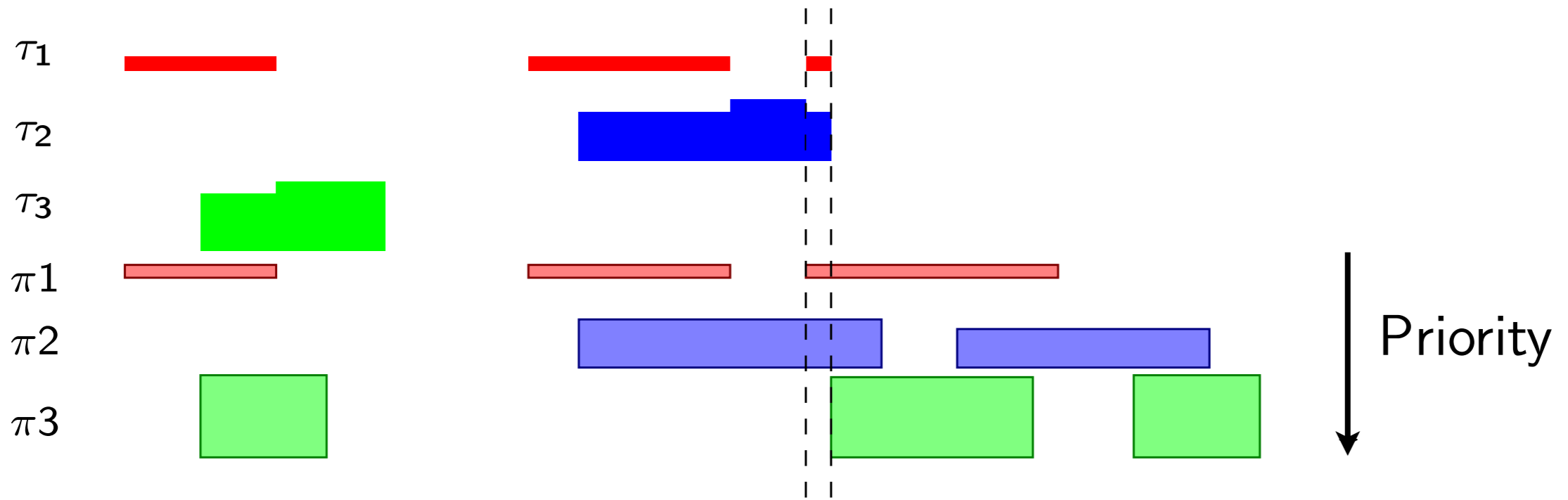
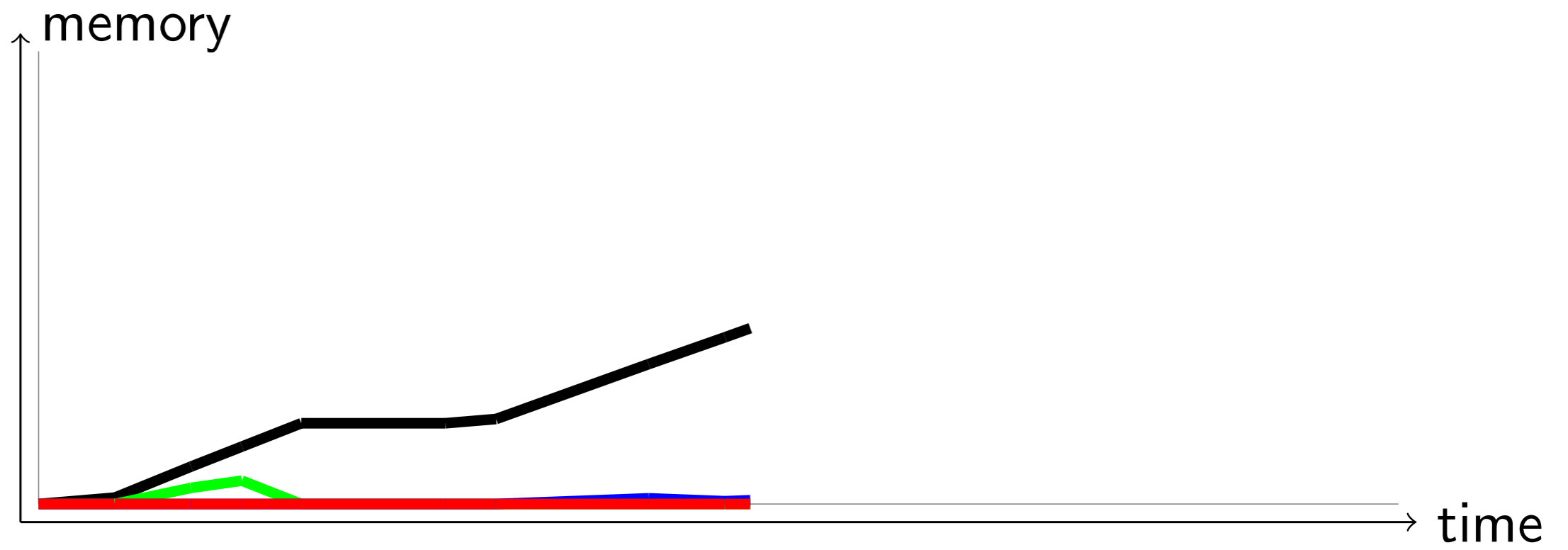


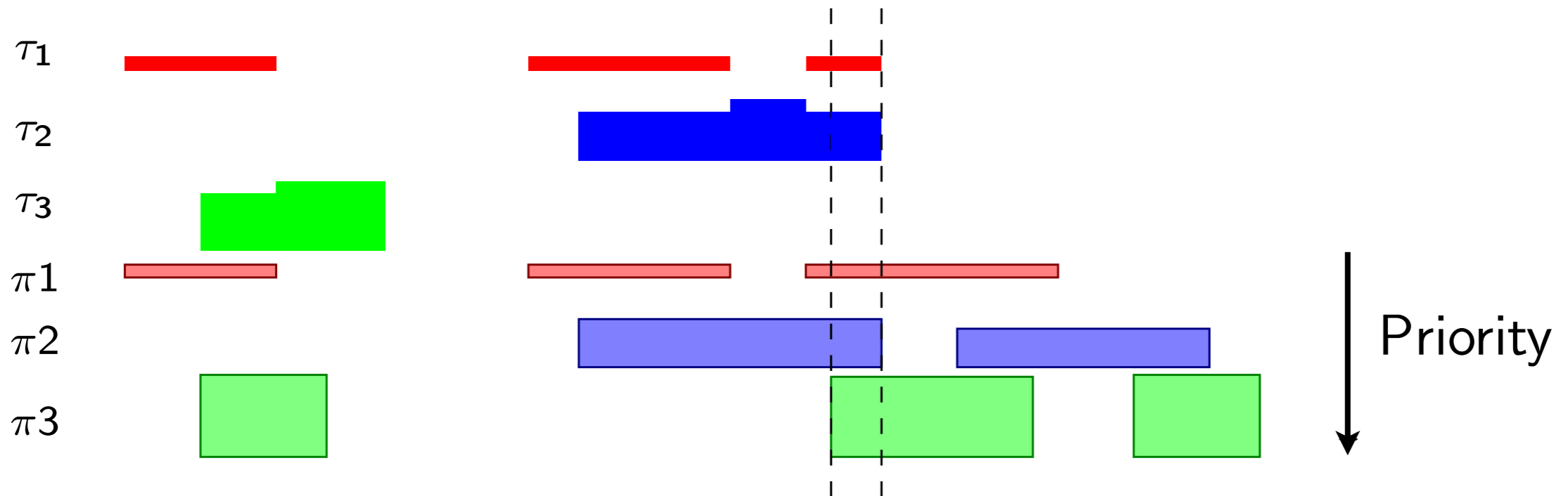
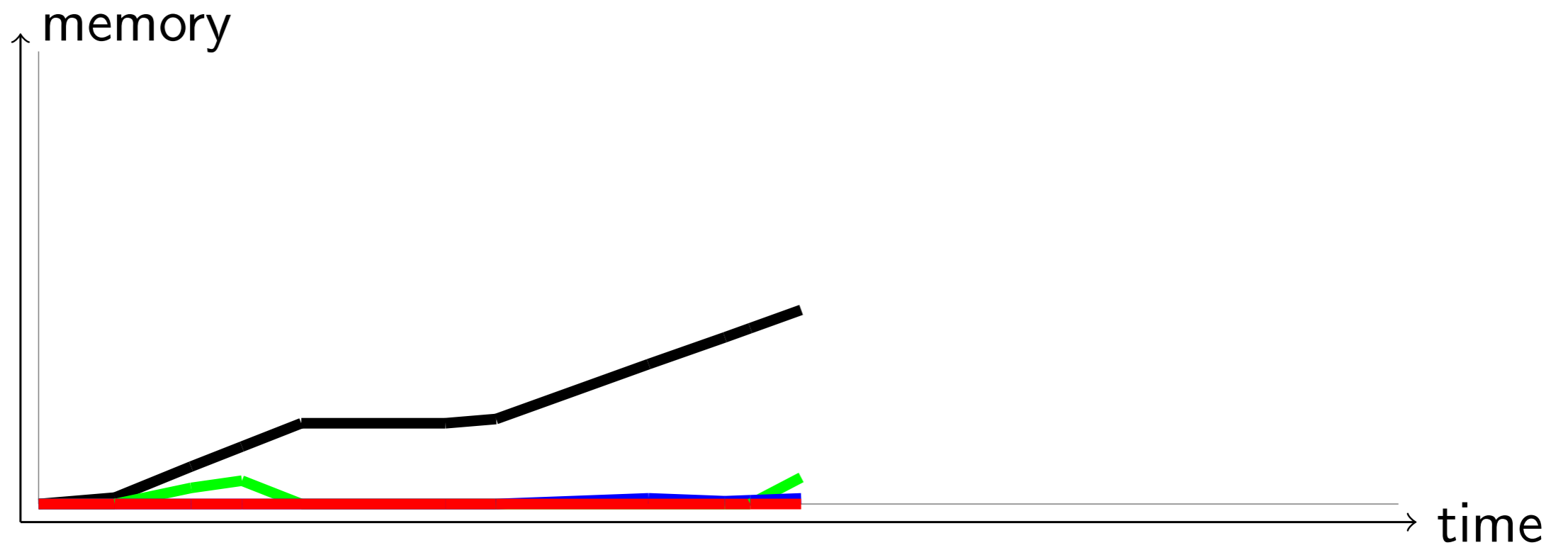


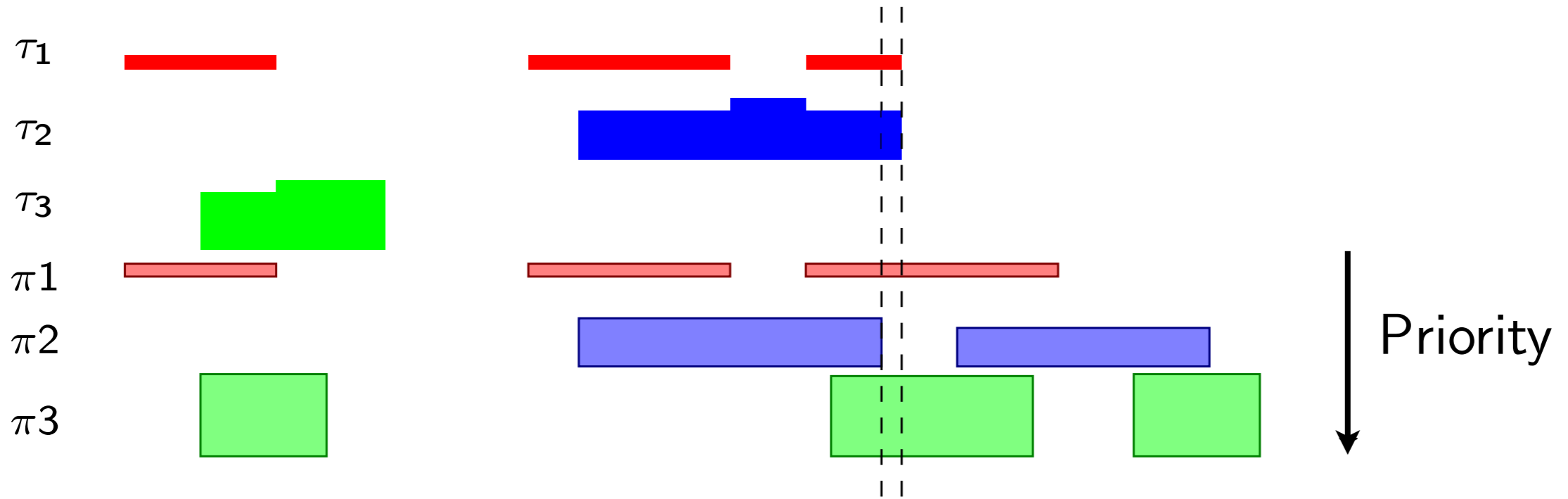
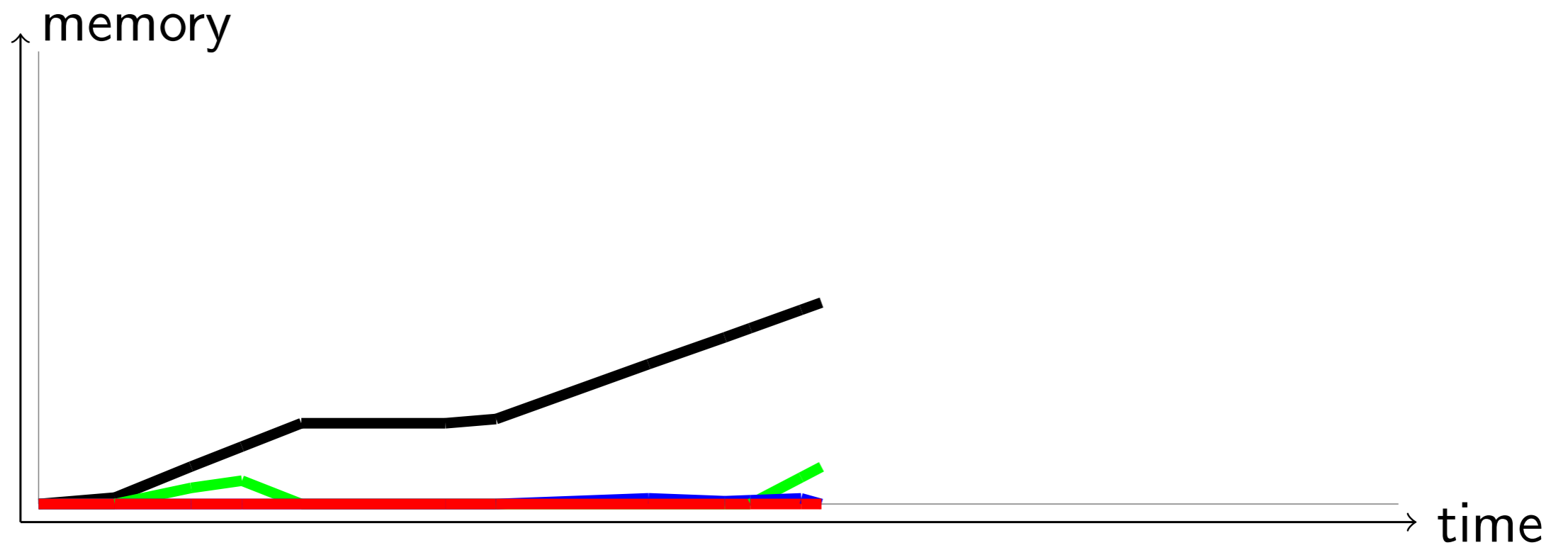


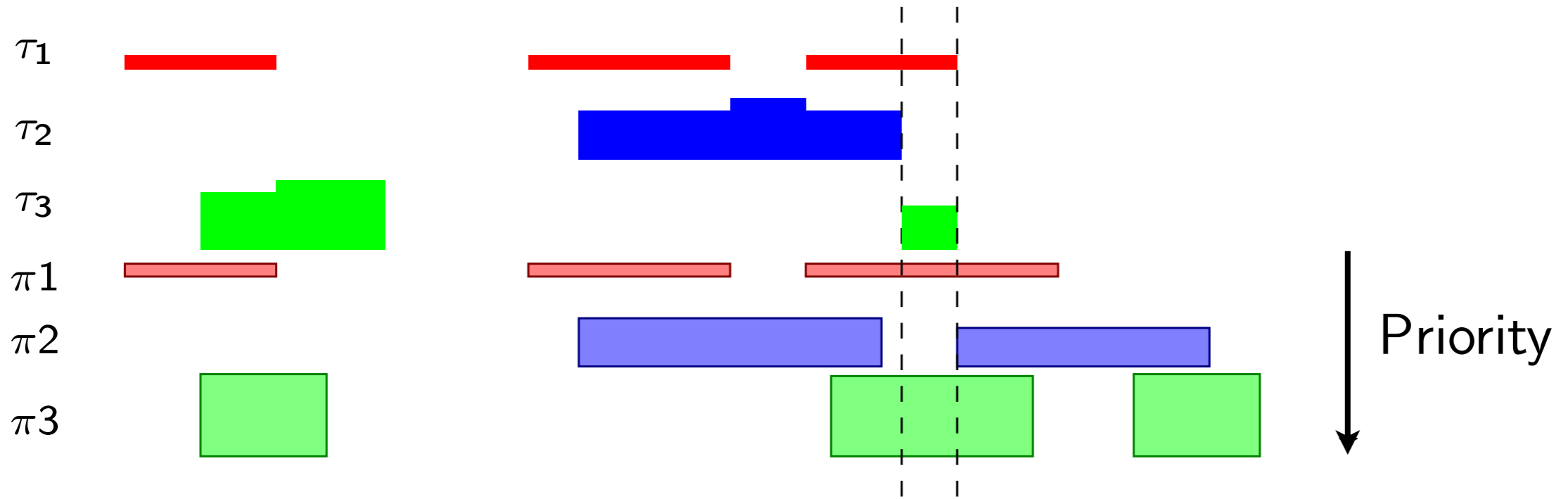
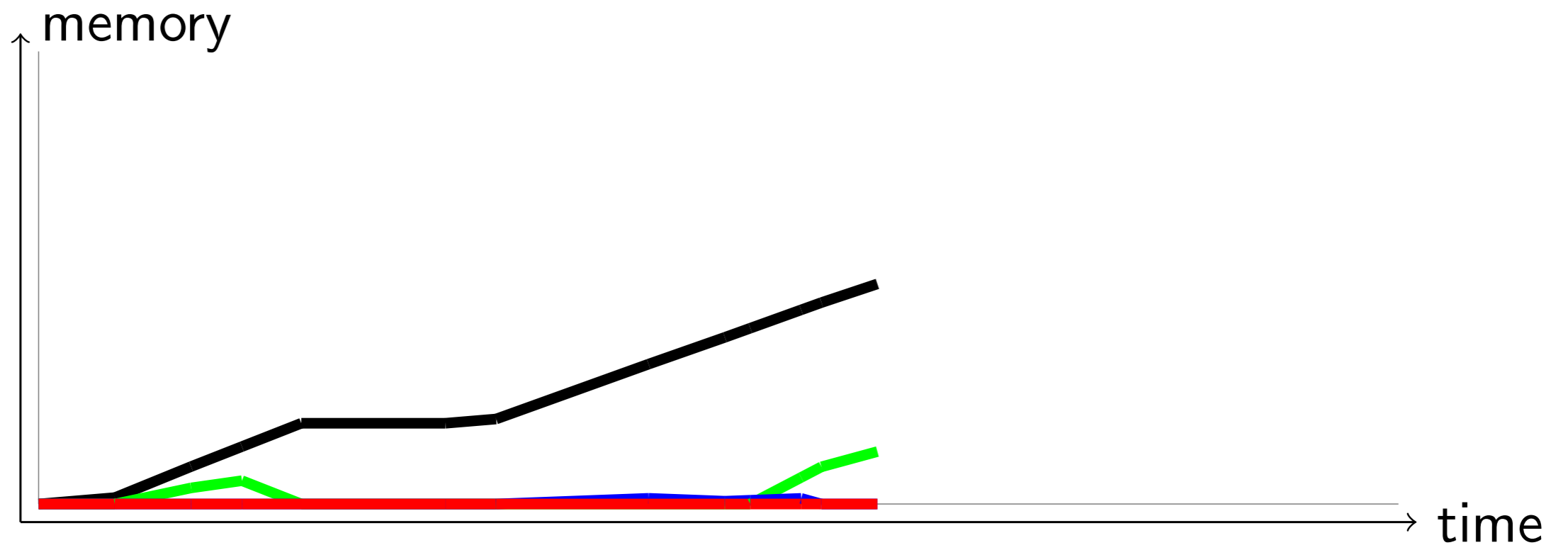




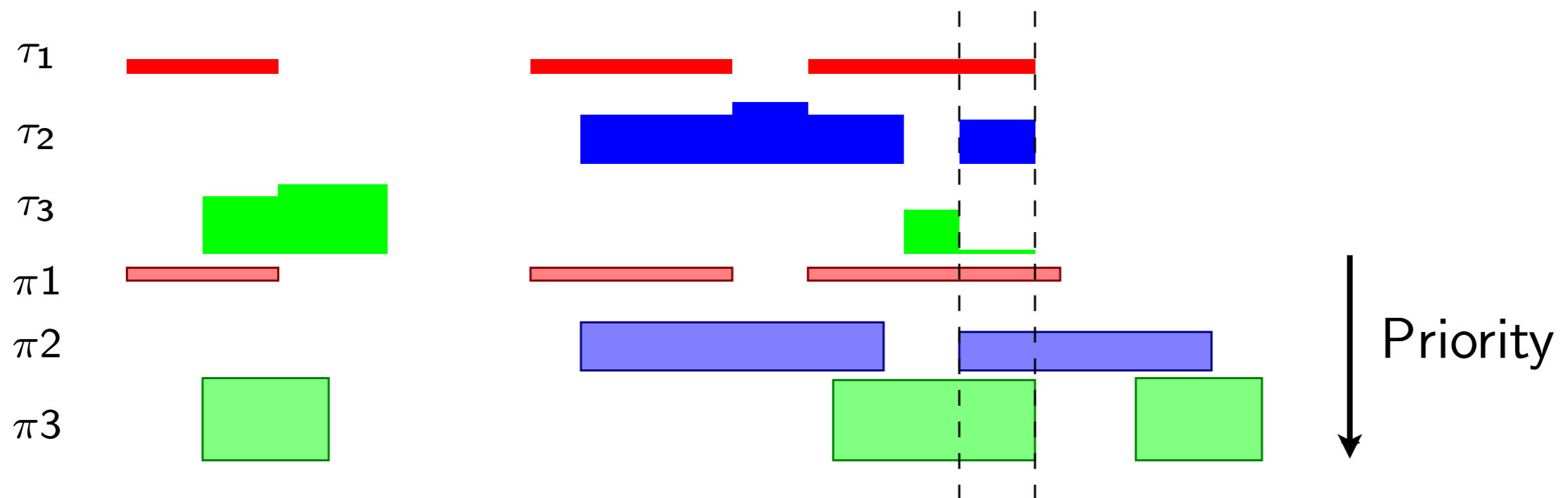
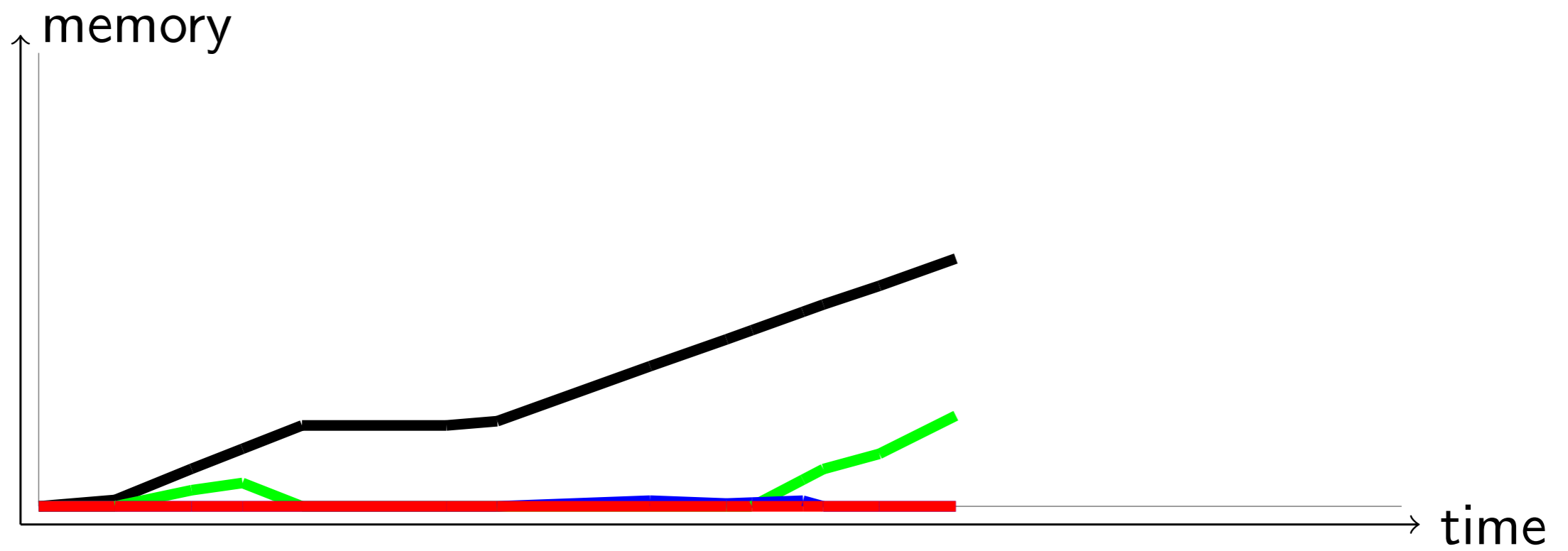


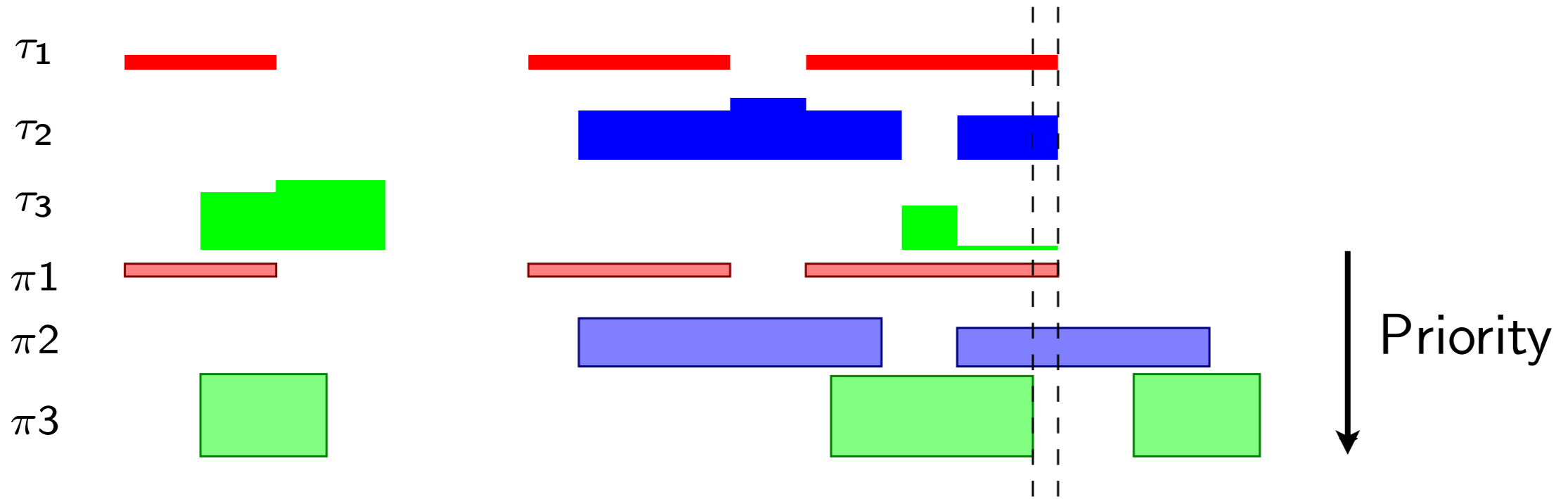
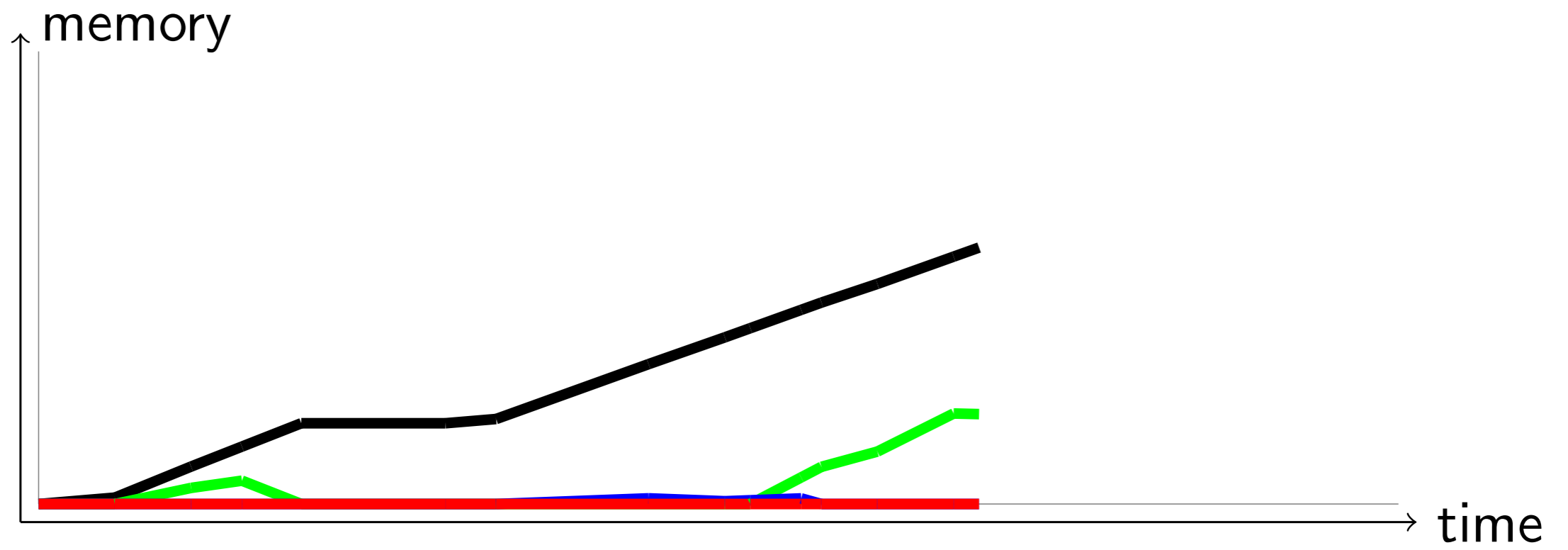


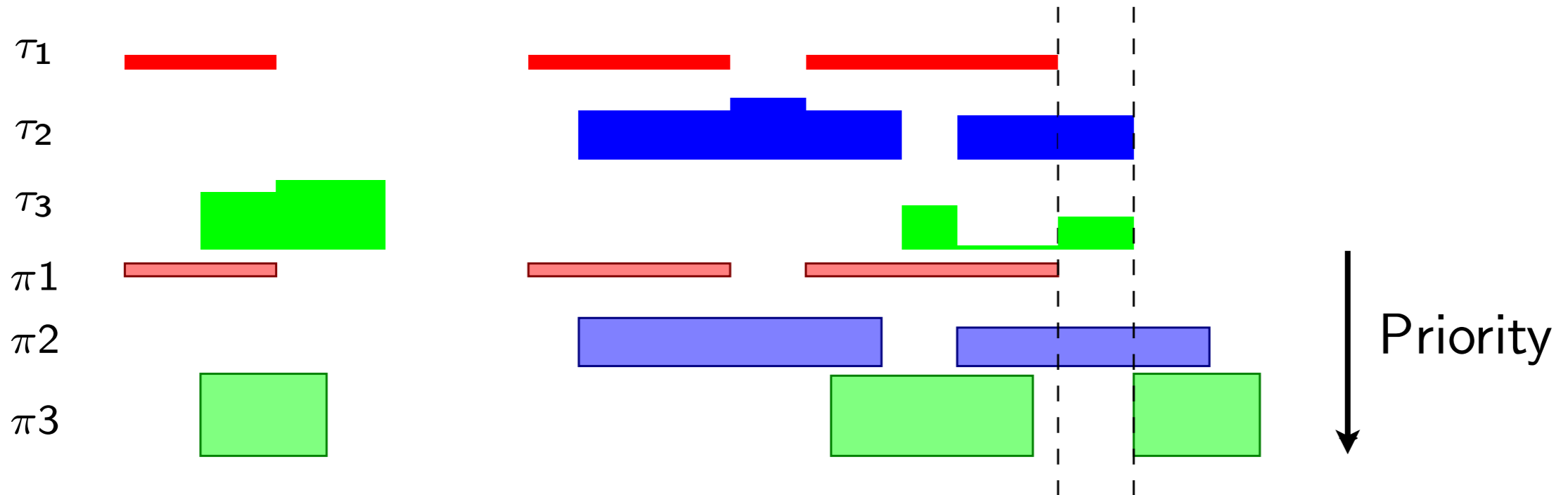
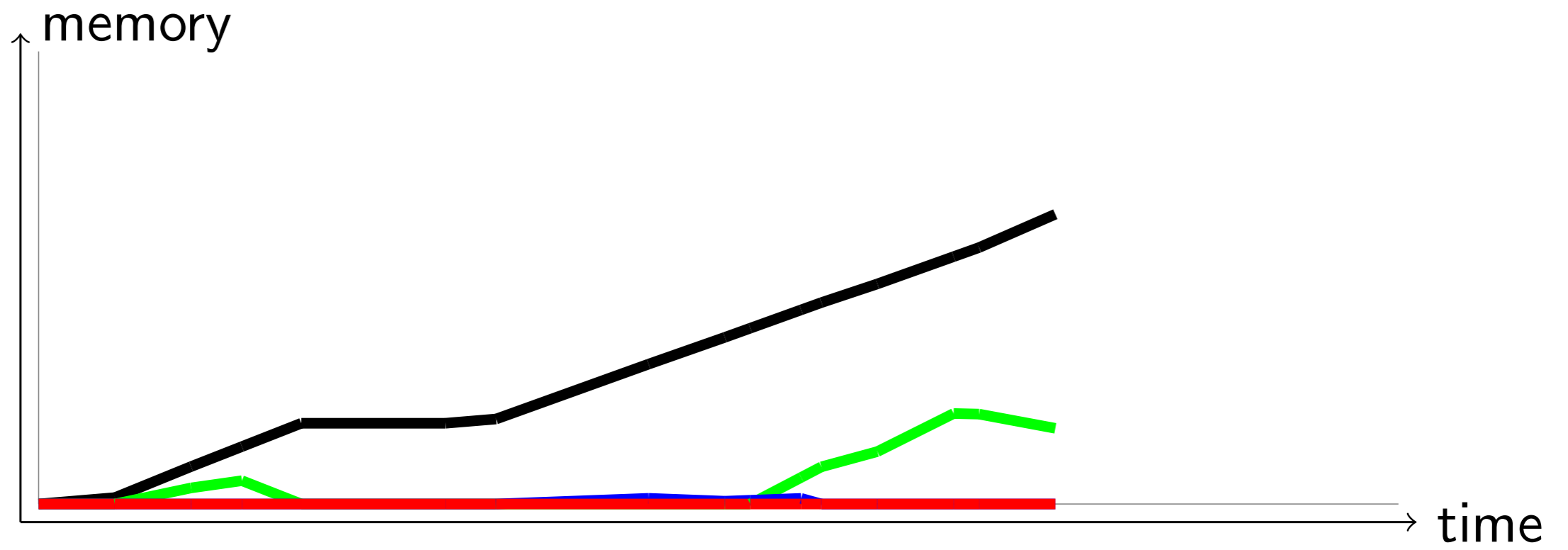


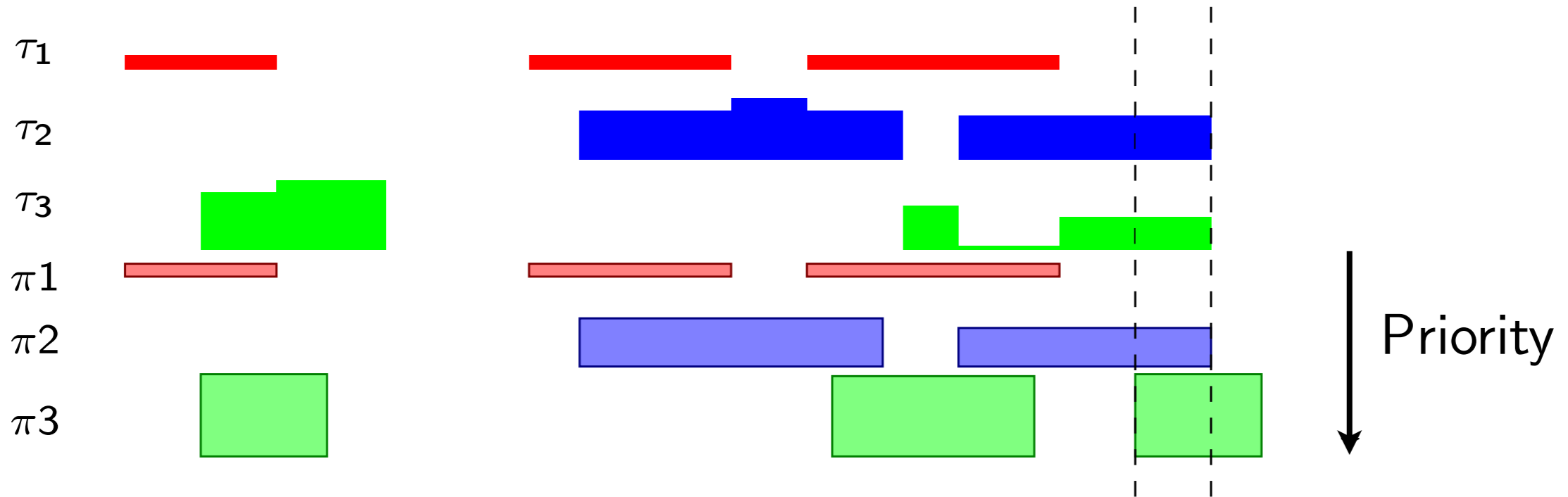
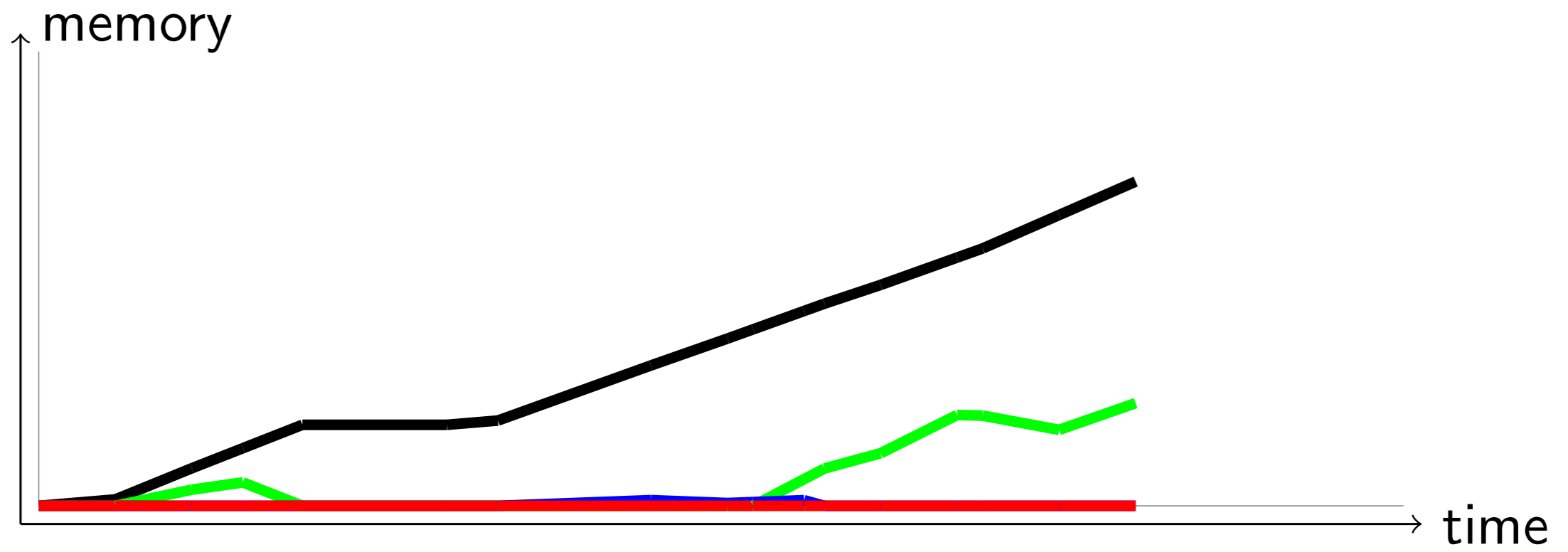


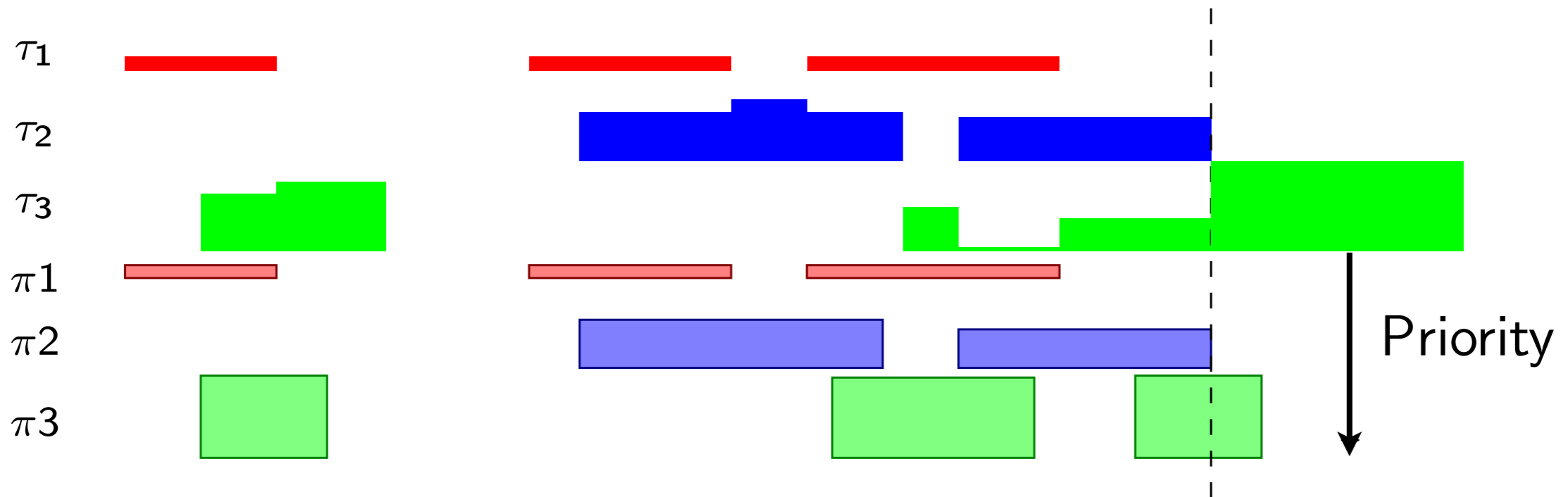
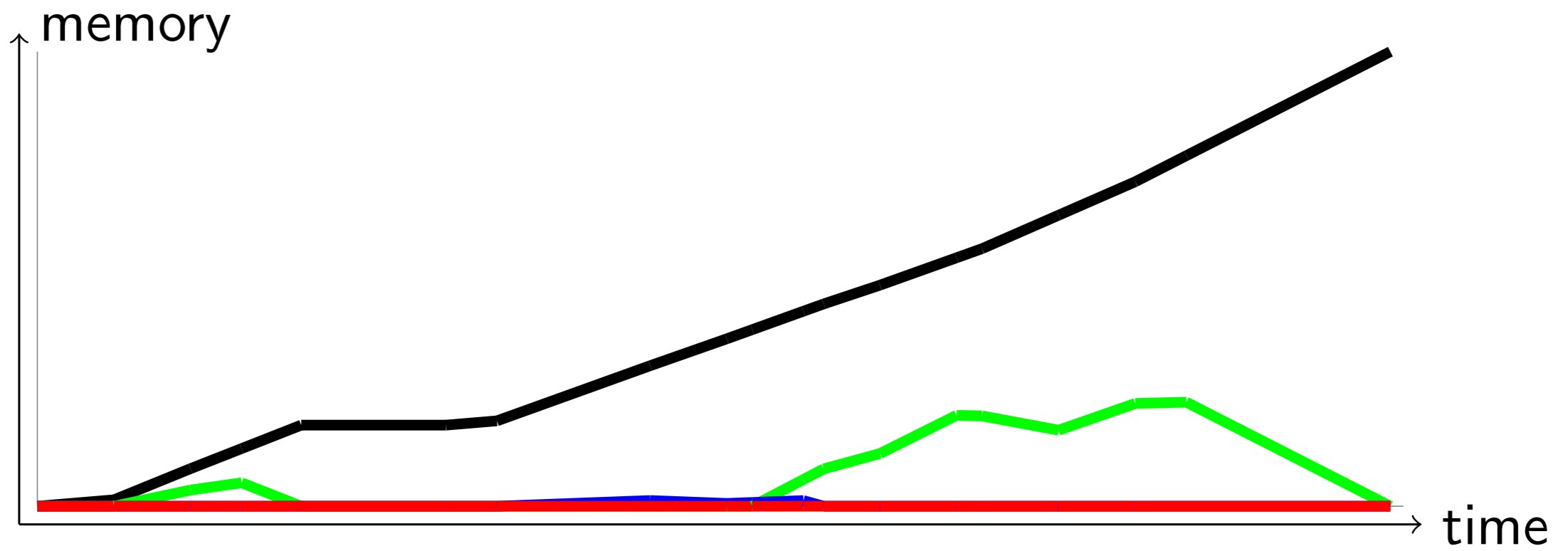






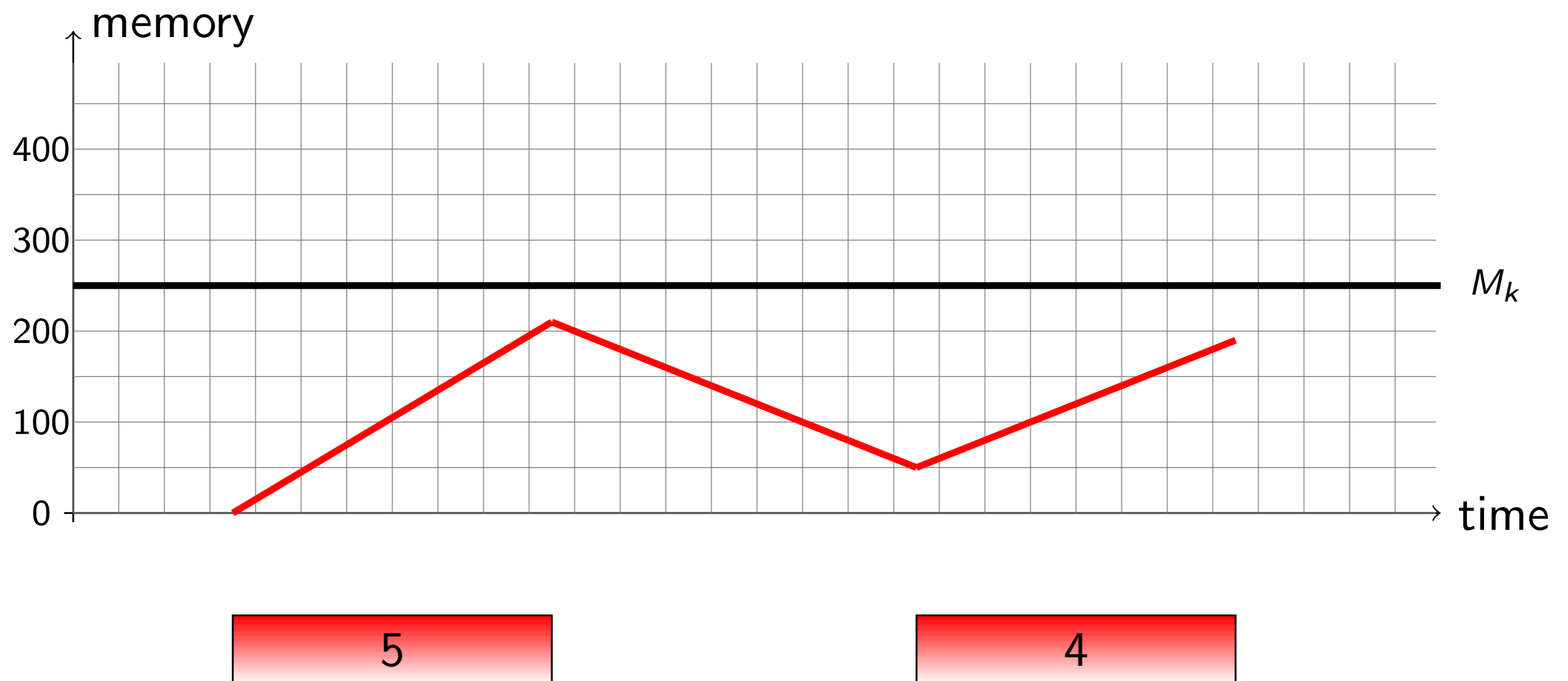






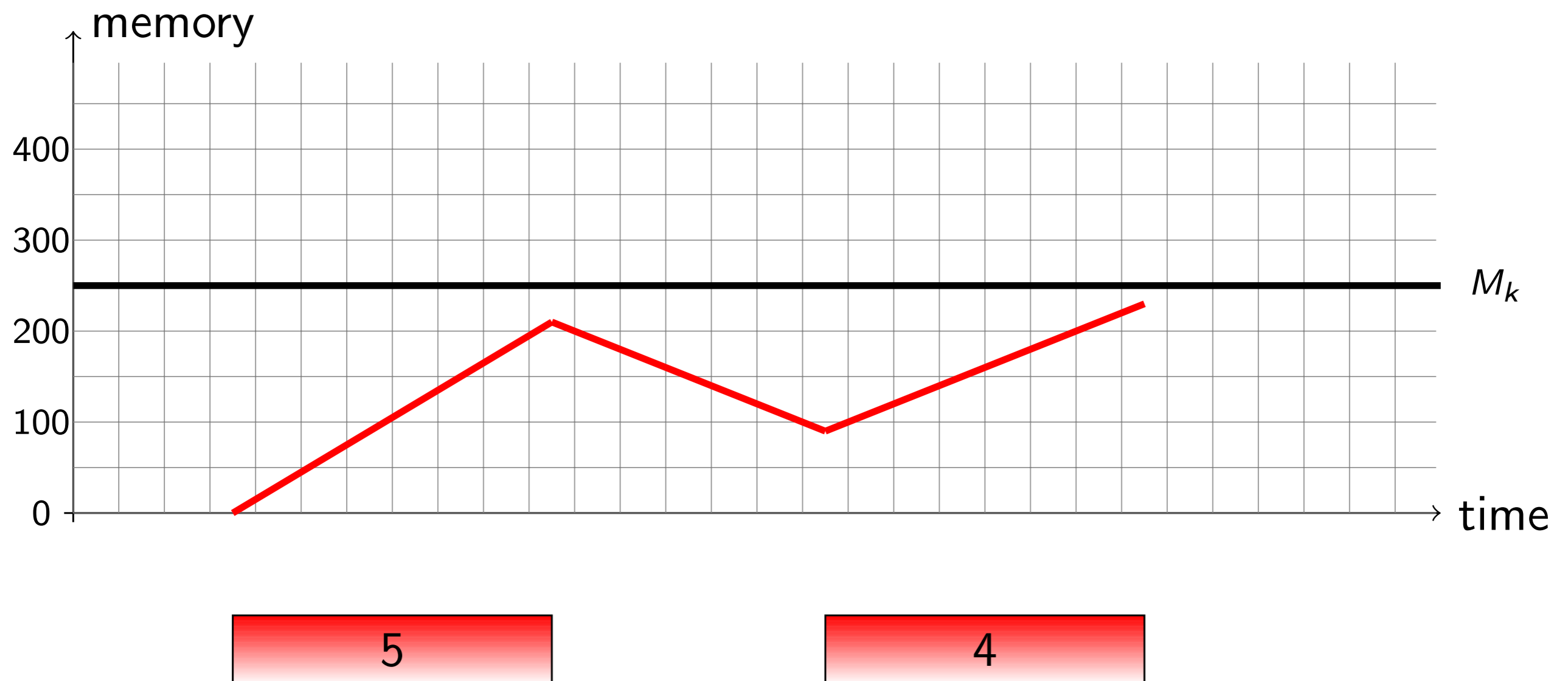
# First filtering algorithm

- We study a list of production tasks  $\Omega$  from an experiment
- Objective: Compute the minimum duration necessary to transfer data without saturating the experiment's memory



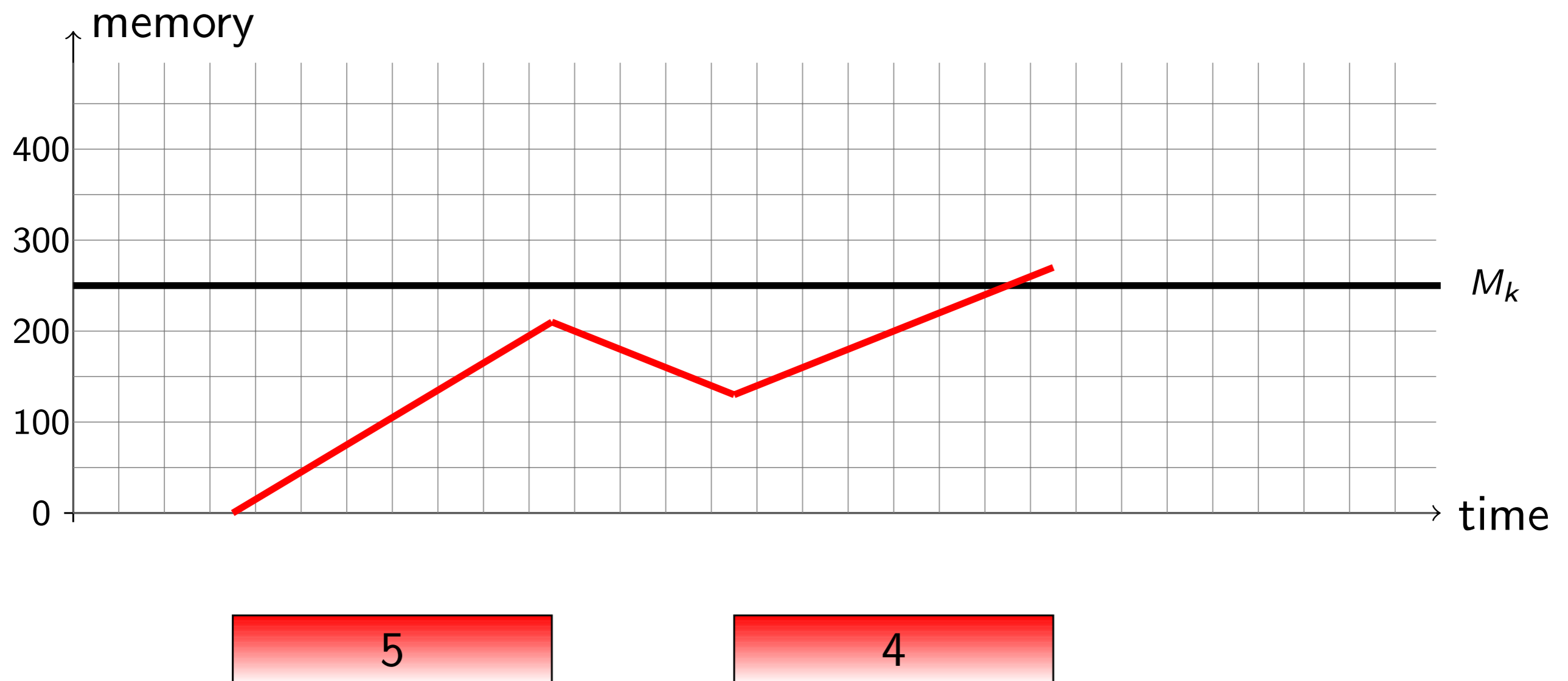
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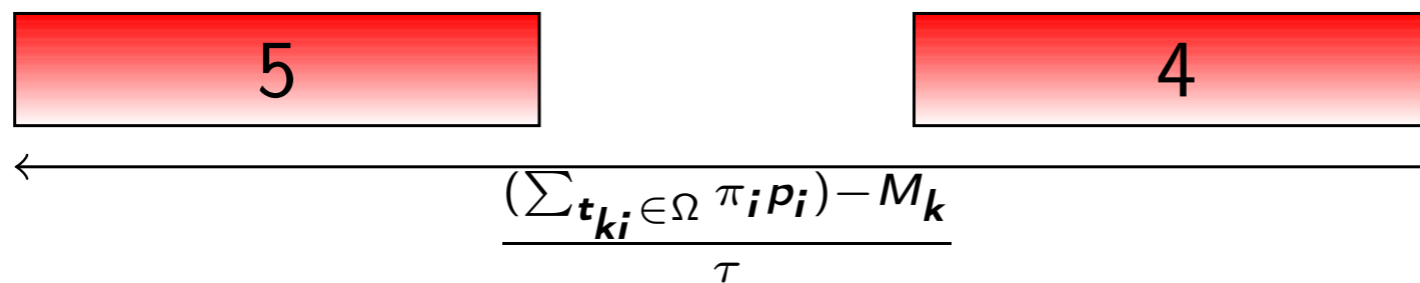
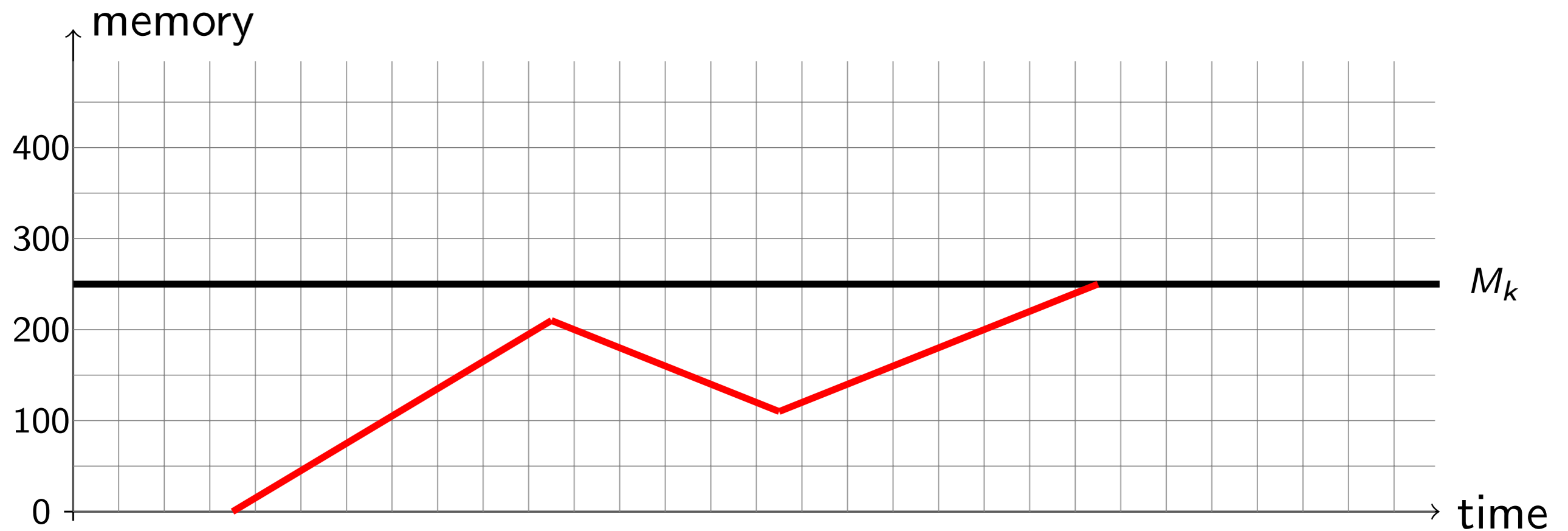
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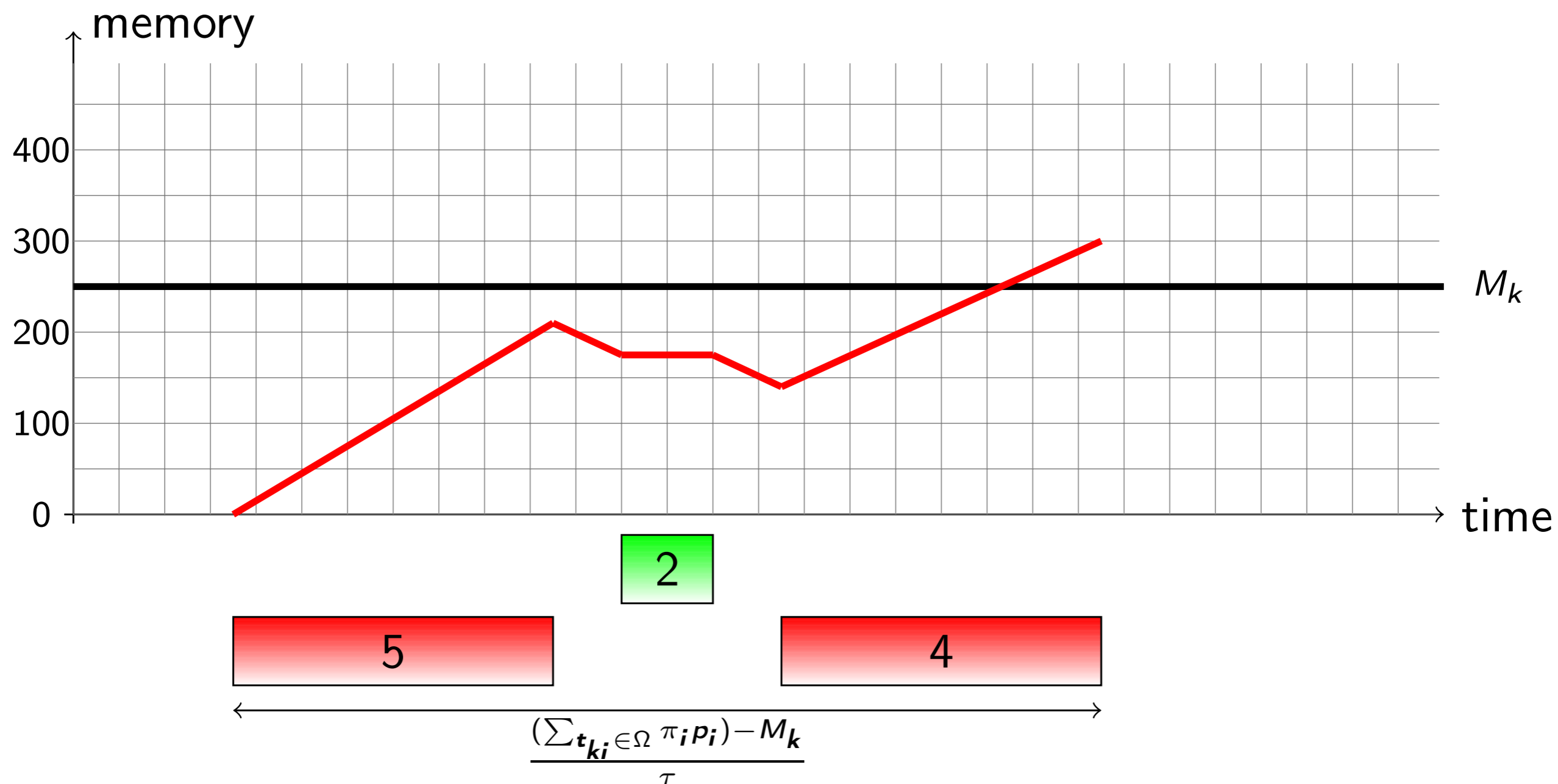
## Rule

- Induce constraint:  $end(t_n) - start(t_1) \geq \frac{(\sum_{t_{ki} \in \Omega} \pi_i p_i) - M_k}{\tau}$



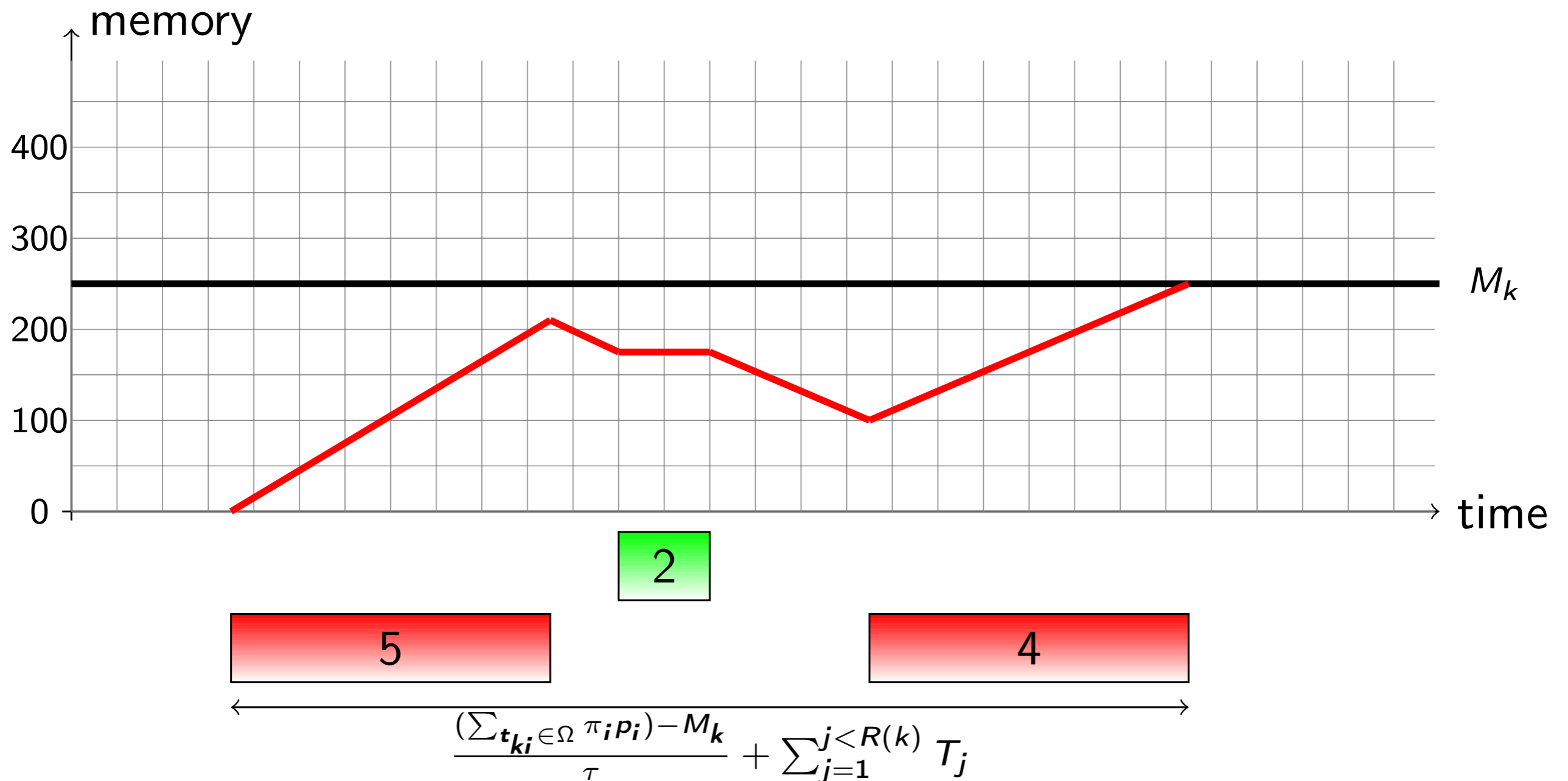
# Improvement

- We can improve the filtering if we take into account the other experiments with a higher priority.



## Improvement

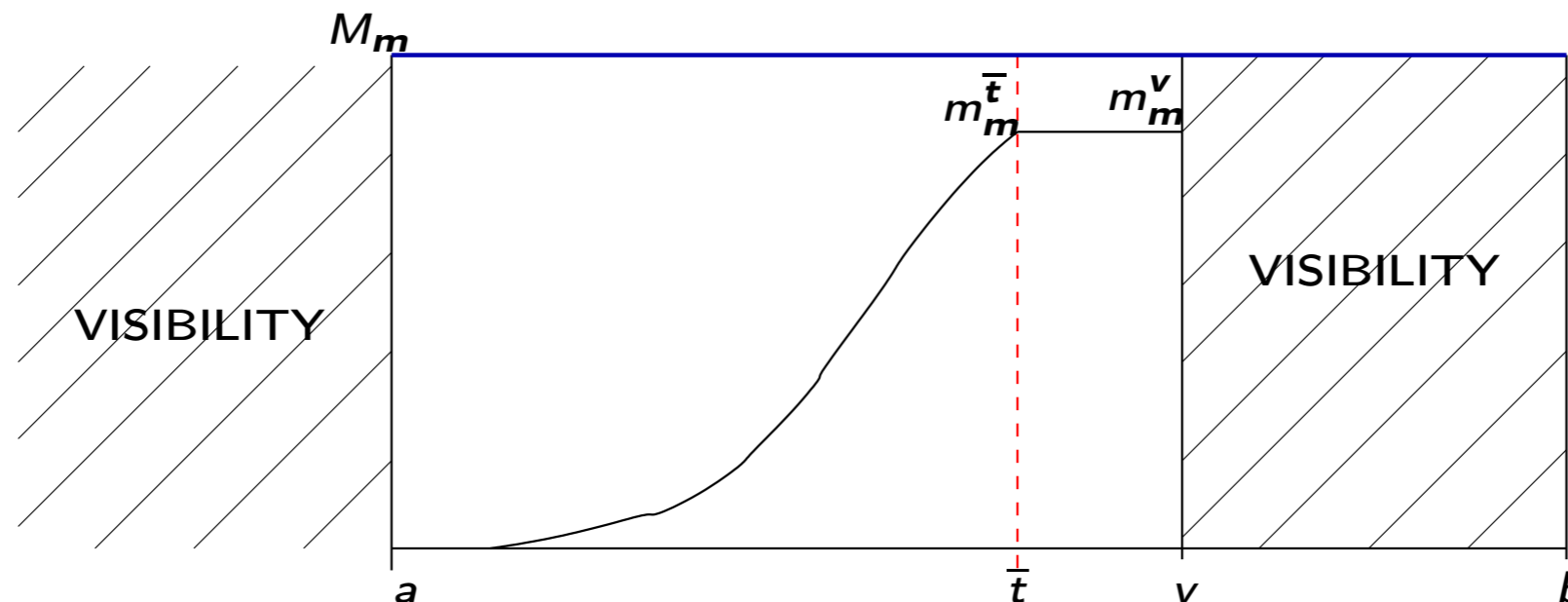
- Constraint:  $end(t_n) - start(t_1) \geq \frac{(\sum_{t_{ki} \in \Omega} \pi_i p_i) - M_k}{\tau} + \sum_{j=1}^{j < R(k)} T_j$



# Second filtering algorithm

## Second rule

- Periods preceding visibility are critical for data loss
  - No transfer to the orbiter is possible
  - Data accumulates on the mass memory
  - At  $\bar{t}$ , the mass memory is saturated
- Data produced after  $\bar{t}$  and before  $v$  must remain in exp memory

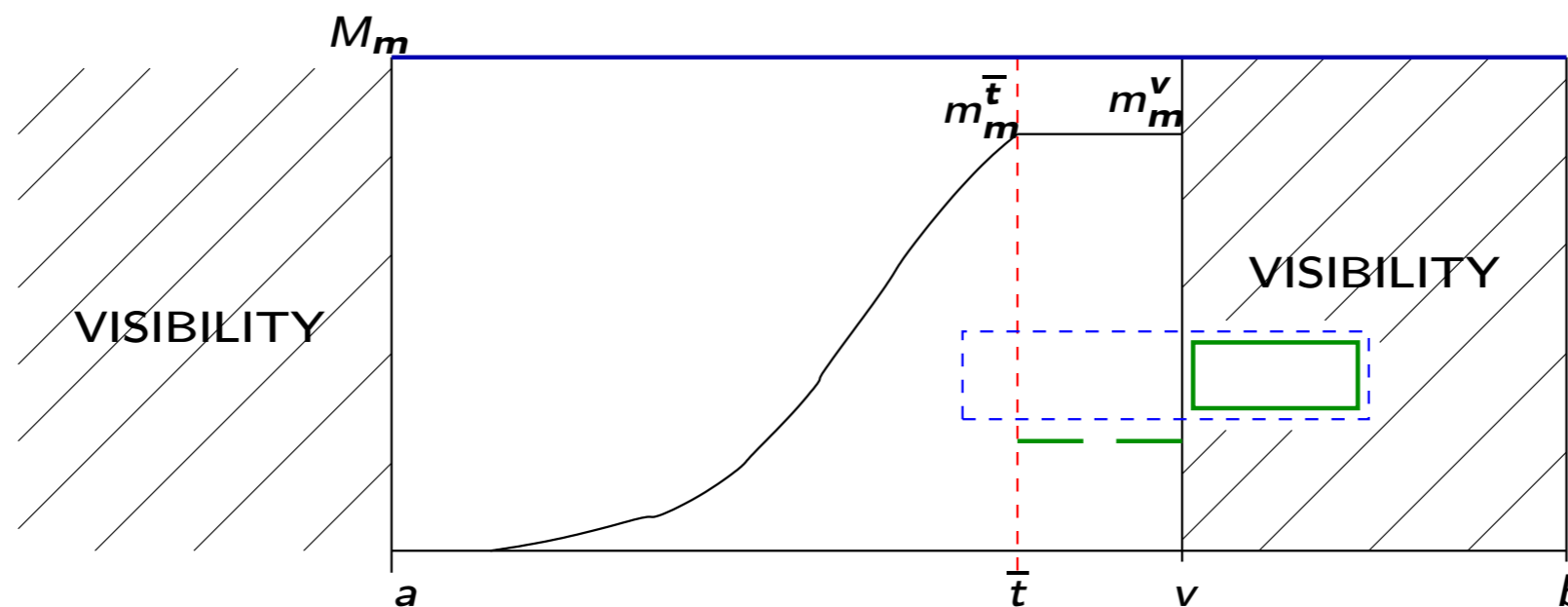


# Second filtering algorithm

## Second rule

- For each experiment  $Exp_k$ :
  - The data produced between  $\bar{t}$  and  $v$  may exceed its capacity
    - Either it should be run earlier when it was possible to transfer
    - Either it should be run later, that is in visibility
  - It induces forbidden interval:

$$|t_{ki} \cap [\bar{t}, v]| \geq \frac{\delta_k - \gamma_k + (|t_{ki} \cap [\bar{t}, v]| * \pi_{ki})}{\pi_{ki}}$$



# Outline

- 1 Problem
  - Data Transfer
  
- 2 Mathematical modeling of transfers
  - A Simplified model of Data Transfer
  
- 3 Algorithms
  - Sweep Algorithm
  - Filtering algorithms
  
- 4 Benchmarks

## Benchmarks

SCENARIO	PARAMETERS		MOST+Ilc-Reservoir		MOST +DataTransfer	
	$M_m$	Visi.	Init. time (s)	CPU time (s)	Init. time (s)	CPU time (s)
Consert	17456	Periodic	4.06	20.07	0.88	0.08
Consert/Romap	17456	Periodic	11.13	Time out	1.17	0.1
Consert/Romap	37456	Periodic	11.03	Time out	1.17	0.1
SD2/Ptolemy	17456	Periodic	26.71	41.72	3.37	0.09
SD2/Ptolemy	17456	Continuous	32.78	79.48	3.25	0.08
SD2/Cosac/Civa	37456	Periodic	50.20	181.91	2.75	0.14
SD2/Cosac/Civa	17456	Periodic	50.84	179.19	2.95	0.15
SD2/Cosac/Civa	17456	Continuous	25.12	91.08	1.82	0.10

Table: Old vs. new version of MOST on 8 standard scenarios





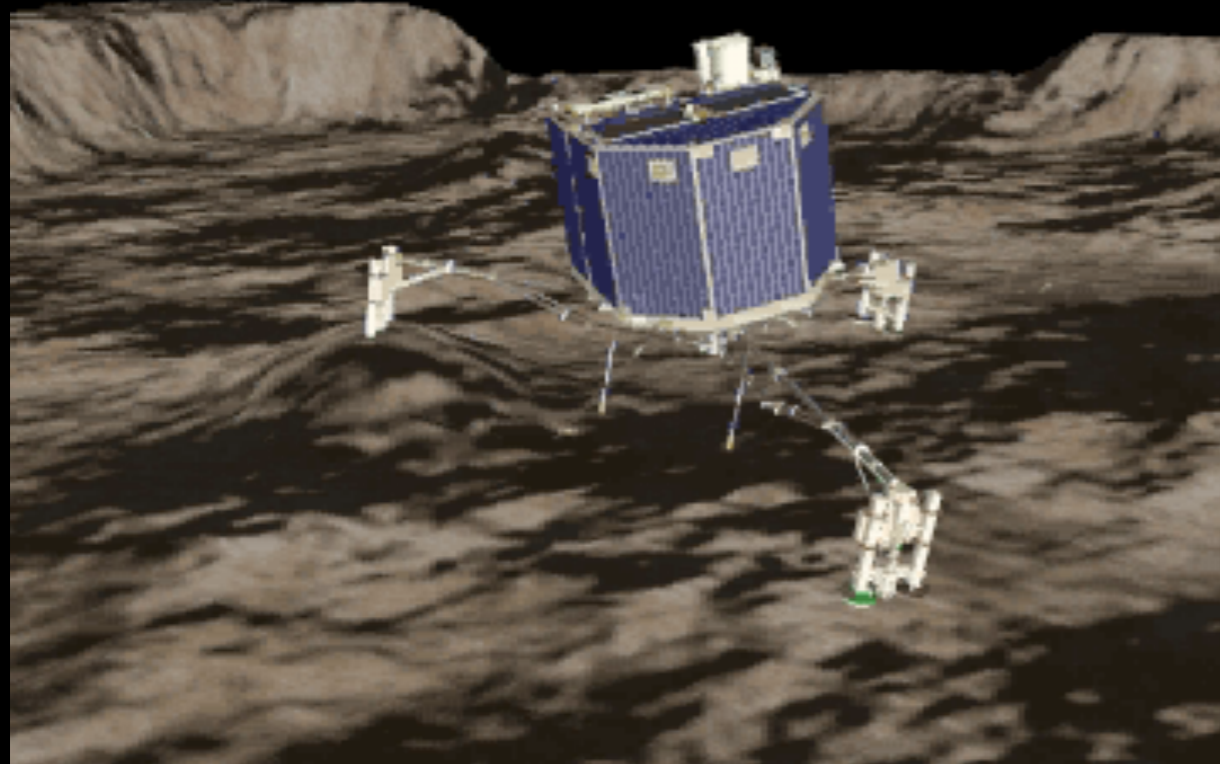
## Resume

### Transfer problem

A better modeling

A Faster transfers computing

Need propagation



### Results

Improvement of computing times

An exact and approximate modeling

Two filtering algorithms

Thank for your attention