

An optimal Arc Consistency algorithm for a chain of Atmost constraints with cardinality

Mohamed Siala , Emmanuel Hebrard, and Marie-José Huguet



Toulouse, France

Outline

The ATMOSTSEQCARD constraint

Filtering the domains

Experimental results

Conclusion & Future work

Definition

$\text{ATMOSTSEQCARD}(u, q, d, [x_1, \dots, x_n]) \Leftrightarrow$

$$\bigwedge_{i=0}^{n-q} \left(\sum_{l=1}^q x_{i+l} \leq u \right) \wedge \left(\sum_{i=1}^n x_i = d \right)$$

Definition

$\text{ATMOSTSEQCARD}(u, q, d, [x_1, \dots, x_n]) \Leftrightarrow$

$$\bigwedge_{i=0}^{n-q} \left(\sum_{l=1}^q x_{i+l} \leq u \right) \wedge \left(\sum_{i=1}^n x_i = d \right)$$

Example $\text{ATMOSTSEQCARD}(2, 4, 4, [x_1, \dots, x_7])$

<u>0</u>	<u>1</u>	<u>1</u>	<u>0</u>	<u>1</u>	<u>1</u>	<u>0</u>		<u>1</u>	<u>1</u>	<u>0</u>	<u>0</u>	<u>1</u>	<u>0</u>	<u>1</u>
—	—	—	—	—	—	—	—	—	—	—	—	—	—	—
		—	—	—	—	—	—			—	—	—	—	—
			—	—	—	—	—			—	—	—	—	—

Context

Sequence Constraints

- Let $[x_1, \dots, x_n]$ be a sequence of integer variables.

Context

Sequence Constraints

- Let $[x_1, \dots, x_n]$ be a sequence of integer variables.
- The AMONG constraint ensures that the number of occurrences of values in $\{v_1..v_k\}$ in a subsequence $[x_{j_1}, \dots, x_{j_q}]$ is bounded between l and u .

Context

Sequence Constraints

- Let $[x_1, \dots, x_n]$ be a sequence of integer variables.
- The AMONG constraint ensures that the number of occurrences of values in $\{v_1..v_k\}$ in a subsequence $[x_{j_1}, \dots, x_{j_q}]$ is bounded between l and u .
- AMONGSEQ : the conjunction of all $n - q + 1$ AMONG on q consecutive variables (i.e. $\bigwedge_{i=0}^{n-q} \text{AMONG}([x_{i+1}, \dots, x_{i+q}])$).

Context

Sequence Constraints

- Let $[x_1, \dots, x_n]$ be a sequence of integer variables.
- The AMONG constraint ensures that the number of occurrences of values in $\{v_1..v_k\}$ in a subsequence $[x_{j_1}, \dots, x_{j_q}]$ is bounded between l and u .
- AMONGSEQ : the conjunction of all $n - q + 1$ AMONG on q consecutive variables (i.e. $\bigwedge_{i=0}^{n-q} \text{AMONG}([x_{i+1}, \dots, x_{i+q}])$).
- GEN-SEQUENCE: Conjunction of (consecutive) AMONG

Context

Sequence Constraints

- Let $[x_1, \dots, x_n]$ be a sequence of integer variables.
- The AMONG constraint ensures that the number of occurrences of values in $\{v_1..v_k\}$ in a subsequence $[x_{j_1}, \dots, x_{j_q}]$ is bounded between l and u .
- AMONGSEQ : the conjunction of all $n - q + 1$ AMONG on q consecutive variables (i.e. $\bigwedge_{i=0}^{n-q} \text{AMONG}([x_{i+1}, \dots, x_{i+q}])$).
- GEN-SEQUENCE: Conjunction of (consecutive) AMONG
- ATMOSTSEQCARD \equiv AMONGSEQ \oplus a cardinality constraint

Context

Sequence Constraints

- Let $[x_1, \dots, x_n]$ be a sequence of integer variables.
 - The AMONG constraint ensures that the number of occurrences of values in $\{v_1..v_k\}$ in a subsequence $[x_{j_1}, \dots, x_{j_q}]$ is bounded between l and u .
 - AMONGSEQ : the conjunction of all $n - q + 1$ AMONG on q consecutive variables (i.e. $\bigwedge_{i=0}^{n-q} \text{AMONG}([x_{i+1}, \dots, x_{i+q}])$).
 - GEN-SEQUENCE: Conjunction of (consecutive) AMONG
 - ATMOSTSEQCARD \equiv AMONGSEQ \oplus a cardinality constraint
- ATMOSTSEQCARD can be encoded with a GEN-SEQUENCE

Context

Sequence Constraints

- Let $[x_1, \dots, x_n]$ be a sequence of integer variables.
 - The AMONG constraint ensures that the number of occurrences of values in $\{v_1..v_k\}$ in a subsequence $[x_{j_1}, \dots, x_{j_q}]$ is bounded between l and u .
 - AMONGSEQ : the conjunction of all $n - q + 1$ AMONG on q consecutive variables (i.e. $\bigwedge_{i=0}^{n-q} \text{AMONG}([x_{i+1}, \dots, x_{i+q}])$).
 - GEN-SEQUENCE: Conjunction of (consecutive) AMONG
 - ATMOSTSEQCARD \equiv AMONGSEQ \oplus a cardinality constraint
- ATMOSTSEQCARD can be encoded with a GEN-SEQUENCE
- ATMOSTSEQCARD can be encoded with a Global Sequencing Constraint (GSC)

Existing complexities

Gen-Sequence

- COST-REGULAR encoding: $O(2^q n)$ [Van Hoesve et al, 2009]
- Gen-Sequence: $O(n^3)$ [Van Hoesve et al, 2009]
- Flow-based Algorithm: $O(n^2)$ [Maher et al, 2008]

GSC

- GCC encoding, Not AC, NP-Hard [Puget and Régin, 1997]

Why the **ATMOSTSEQCARD** constraint? [1]

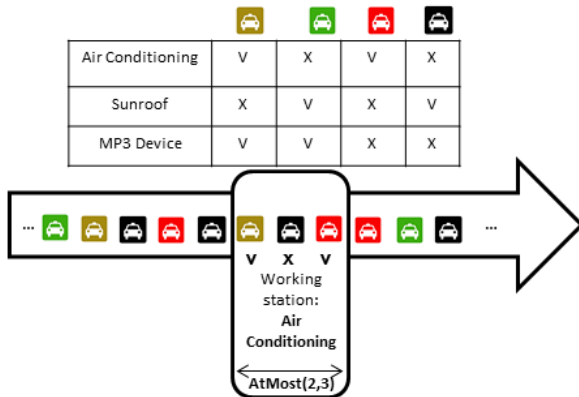


Figure: The car-sequencing problem

Why the ATMOSTSEQCARD constraint? [2]

7 days, 4 employees, 3 periods, 40h per week, Atmost(1,3)

	D	E	N	D	E	N	D	E	N	D	E	N	D	E	N	D	E	N	d			
emp ₁	0	1	0	0	0	1	0	0	0	1	0	0	0	0	0	1	0	0	1	0	0	5
emp ₂	1	0	0	1	0	0	0	0	0	0	1	0	0	1	0	0	0	0	1	0	0	5
emp ₃	0	0	0	1	0	0	1	0	0	0	0	1	0	0	0	0	0	1	0	0	1	5
emp ₄	0	1	0	0	0	1	0	0	1	0	0	0	1	0	0	1	0	0	0	0	0	5

Table: Crew-rostering problem

The proposed algorithm

- Let (x_1, \dots, x_n) be a boolean sequence subject to $\text{ATMOSTSEQCARD}(u, q, d, [x_1, \dots, x_n])$
- Our filtering algorithm is based on a greedy procedure (denoted by `leftmost`).
- `leftmost`: computes an assignment w maximizing the cardinality of the sequence with respect to the `ATMOST` constraints.

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	1	2	^c 3	4	<i>max</i>
.	0					
0	0					
.	0					
1	1					
.	0					
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

	x_i	w	1	2	^c 3	4	<i>max</i>
→	.	—	0	0			
	0		0				
	.		0				
	1		1				
	.		0				
	.		0				
	.		0				
	0		0				
	.		0				
	0		0				
	1		1				
	.		0				
	.		0				
	1		1				
	.		0				
	.		0				

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

	x_i		w		c				max
				1	2	3	4		
→	.	—	0	0	0				
	0	—	0						
	.		0						
	1		1						
	.		0						
	.		0						
	.		0						
	0		0						
	.		0						
	0		0						
	1		1						
	.		0						
	.		0						
	1		1						
	.		0						
	.		0						

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

	x_i	w		1	2	3	4	max
\rightarrow	.	—	0	0	0	0		
	0	—	0					
	.	—	0					
	1		1					
	.		0					
	.		0					
	.		0					
	0		0					
	.		0					
	0		0					
	1		1					
	.		0					
	.		0					
	1		1					
	.		0					
	.		0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

	x_i	w	c				max
			1	2	3	4	
→	.	—	0	0	0	0	1
	0	—	0				
	.	—	0				
	1	—	1				
	.		0				
	.		0				
	.		0				
	0		0				
	.		0				
	0		0				
	1		1				
	.		0				
	.		0				
	1		1				
	.		0				
	.		0				

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	0	0	0	0	1	1
0	0					
.	0					
1	1					
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0					
.	0					
1	1					
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

	x_i		w	1	2	3	4	max
	.	—	1	0	0	0	1	1
→	0	—	0	1				
	.		0					
	1		1					
	.		0					
	.		0					
	.		0					
	0		0					
	.		0					
	0		0					
	1		1					
	.		0					
	.		0					
	1		1					
	.		0					
	.		0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

	x_i	w	1	2	^c 3	4	<i>max</i>
	.	—	1	0	0	0	1
→	0	—	0	1	1		
	.	—	0				
	1		1				
	.		0				
	.		0				
	.		0				
	0		0				
	.		0				
	0		0				
	1		1				
	.		0				
	.		0				
	1		1				
	.		0				
	.		0				

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

	x_i	w	c				max	
			1	2	3	4		
	.	—	1	0	0	0	1	1
→	0	—	0	1	1	2		
	.	—	0					
	1	—	1					
	.		0					
	.		0					
	.		0					
	0		0					
	.		0					
	0		0					
	1		1					
	.		0					
	.		0					
	1		1					
	.		0					
	.		0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

	x_i	w	c				max
			1	2	3	4	
	.	1	0	0	0	1	1
→	0	—	0	1	2	1	
	.	—	0				
	1	—	1				
	.	—	0				
	.		0				
	.		0				
	0		0				
	.		0				
	0		0				
	1		1				
	.		0				
	.		0				
	1		1				
	.		0				
	.		0				

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0					
1	1					
.	0					
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0					
1	1					
.	0					
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	—	1	0	0	0	1
0	—	0	1	1	2	2
→	—	0	1			
1		1				
.		0				
.		0				
.		0				
0		0				
.		0				
0		0				
1		1				
.		0				
.		0				
1		1				
.		0				
.		0				

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	—	1	0	0	0	1
0	—	0	1	1	2	2
→	—	0	1	2		
1	—	1				
.		0				
.		0				
.		0				
0		0				
.		0				
0		0				
1		1				
.		0				
.		0				
1		1				
.		0				
.		0				

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i		w		c				max
			1	2	3	4		
.		1	0	0	0	0	1	1
0	—	0	1	1	2	1	1	2
→ .	—	0	1	2	1			
1	—	1						
.	—	0						
.		0						
.		0						
0		0						
.		0						
0		0						
1		1						
.		0						
.		0						
1		1						
.		0						
.		0						

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
→	—	0	1	2	1	1
1	—	1				
.	—	0				
.	—	0				
.	0	0				
0	0	0				
.	0	0				
0	0	0				
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1					
.	0					
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1					
.	0					
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	—	1	0	0	0	1
0	—	0	1	1	2	2
.	—	0	1	2	1	2
→	—	1	2			
.		0				
.		0				
.		0				
0		0				
.		0				
0		0				
1		1				
.		0				
.		0				
1		1				
.		0				
.		0				

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	— 0	1	1	2	1	2
.	— 0	1	2	1	1	2
→ 1	— 1	2	1			
.	— 0					
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	—	0	1	2	1	2
→	—	1	2	1	1	
.	—	0				
.	—	0				
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
→	1	—	1	2	1	1
.	—	0				
.	—	0				
.	—	0				
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	0					
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	0					
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	— 0	1	1	2	1	2
.	— 0	1	2	1	1	2
1	— 1	2	1	1	1	2
→ .	— 0	1				
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	—	0	1	2	1	2
1	—	1	2	1	1	2
→ .	—	0	1	1		
.	—	0				
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	—	1	2	1	1	2
→ .	—	0	1	1	1	
.	—	0				
.	—	0				
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
→ .	— 0	1	1	1	0	
.	— 0					
.	— 0					
0	— 0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	0	1	1	1	0	1
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	1	1	1	1	0	1
.	0					
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	— 0	1	2	1	1	2
1	— 1	2	1	1	1	2
.	— 1	1	1	1	0	1
→ .	— 0	2				
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	—	1	2	1	1	2
.	—	1	1	1	1	0
→ .	—	0	2	2		
.	—	0				
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	1	1	1	1	0	1
→ .	0	2	2	1		
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	1	1	1	1	0	1
→ .	— 0	2	2	1	0	
.	— 0					
0	— 0					
.	— 0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	1	1	1	1	0	1
.	0	2	2	1	0	2
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	1	1	1	1	0	1
.	0	2	2	1	0	2
.	0					
0	0					
.	0					
0	0					
1	1					
.	0					
.	0					
1	1					
.	0					
.	0					

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	1	1	1	1	0	1
.	0	2	2	1	0	2
.	0	2	1	0	0	2
0	0	1	0	0	1	1
.	1	0	0	1	1	1
0	0	0	2	2	1	2
1	1	2	2	1	2	2
.	0	2	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	1	1	1	1	0	1
.	0	2	2	1	0	2

$$\vec{w} = \text{leftmost} (u = 2, q = 4)$$

x_i	w	c				max
		1	2	3	4	
.	1	0	0	0	1	1
0	0	1	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	1	1	1	1	0	1
.	0	2	2	1	0	2
.	0	2	1	0	0	2
0	0	1	0	0	1	1
.	1	0	0	1	1	1
0	0	0	2	2	1	2
1	1	2	2	1	2	2
.	0	2	1	2	1	2
.	0	1	2	1	1	2
1	1	2	1	1	1	2
.	1	1	1	1	0	1
.	0	2	2	1	0	2

→ Complexity = $O(n.q)$

leftmost_count

- $\text{leftmost_count}([x_1, \dots, x_n], u, q, d)$: a linear time implementation of `leftmost` but returning the maximum cardinality that we can add to the sequence until i .

`leftmost_count`

- `leftmost_count`($[x_1, \dots, x_n], u, q, d$): a linear time implementation of `leftmost` but returning the maximum cardinality that we can add to the sequence until i .
- L (resp. R): the result of `leftmost_count` from left to right (resp. right to left).

leftmost_count

- `leftmost_count`($[x_1, \dots, x_n], u, q, d$): a linear time implementation of `leftmost` but returning the maximum cardinality that we can add to the sequence until i .
- L (resp. R): the result of `leftmost_count` from left to right (resp. right to left).
- Example:

$\mathcal{D}(x_i)$.	0	...	0	1	0	...	1															
<code>leftmost[i]</code>	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1	
<code>leftmost_count[i]</code>	0	1	1	2	3	4	4	4	4	4	4	4	5	6	7	7	7	7	8	8	9	10	10

- $O(n)$ implementation

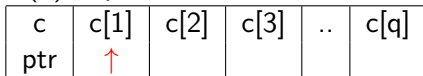
leftmost_count

- `leftmost_count`($[x_1, \dots, x_n], u, q, d$): a linear time implementation of `leftmost` but returning the maximum cardinality that we can add to the sequence until i .
- L (resp. R): the result of `leftmost_count` from left to right (resp. right to left).
- Example:

```

D(xi)      . 0 . . . . . 0 1 0 . . . . . 1
leftmost[i]  1 0 1 1 1 0 0 0 0 1 0 1 1 1 0 0 0 1 0 1 1 1
leftmost_count[i] 0 1 1 2 3 4 4 4 4 4 4 5 6 7 7 7 7 8 8 9 10 10
    
```

- $O(n)$ implementation



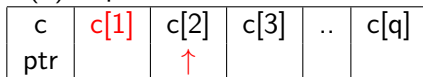
leftmost_count

- `leftmost_count`($[x_1, \dots, x_n], u, q, d$): a linear time implementation of `leftmost` but returning the maximum cardinality that we can add to the sequence until i .
- L (resp. R): the result of `leftmost_count` from left to right (resp. right to left).
- Example:

```

D(xi)      . 0 . . . . . 0 1 0 . . . . . 1
leftmost[i]  1 0 1 1 1 0 0 0 0 1 0 1 1 1 0 0 0 1 0 1 1 1
leftmost_count[i] 0 1 1 2 3 4 4 4 4 4 4 5 6 7 7 7 7 8 8 9 10 10
    
```

- $O(n)$ implementation



leftmost_count

- `leftmost_count`($[x_1, \dots, x_n], u, q, d$): a linear time implementation of `leftmost` but returning the maximum cardinality that we can add to the sequence until i .
- L (resp. R): the result of `leftmost_count` from left to right (resp. right to left).
- Example:

```

D(xi)      . 0 . . . . . 0 1 0 . . . . . 1
leftmost[i]  1 0 1 1 1 0 0 0 0 1 0 1 1 1 0 0 0 1 0 1 1 1
leftmost_count[i] 0 1 1 2 3 4 4 4 4 4 4 5 6 7 7 7 7 8 8 9 10 10
    
```

- $O(n)$ implementation

c	c[1]	c[2]	c[3]	..	c[q]
ptr			↑	..	

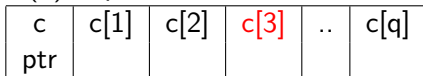
leftmost_count

- `leftmost_count`($[x_1, \dots, x_n], u, q, d$): a linear time implementation of `leftmost` but returning the maximum cardinality that we can add to the sequence until i .
- L (resp. R): the result of `leftmost_count` from left to right (resp. right to left).
- Example:

```

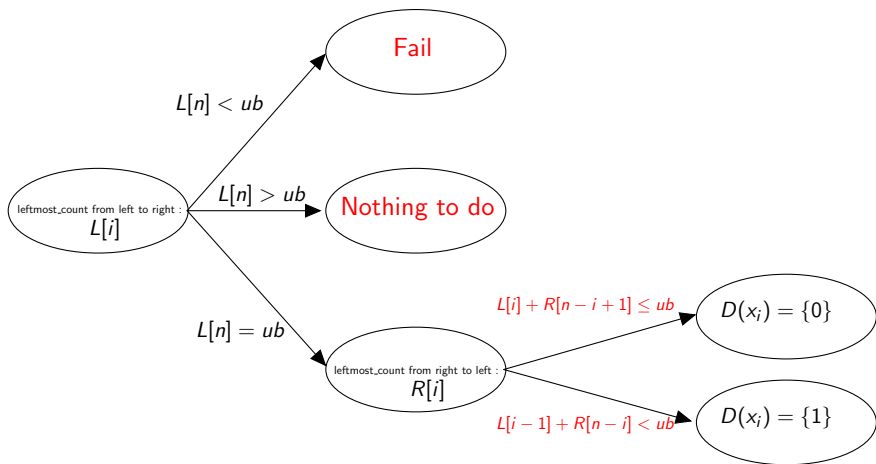
D(xi)      . 0 . . . . . 0 1 0 . . . . . 1
leftmost[i]  1 0 1 1 1 0 0 0 0 1 0 1 1 1 0 0 0 1 0 1 1 1
leftmost_count[i] 0 1 1 2 3 4 4 4 4 4 4 5 6 7 7 7 7 8 8 9 10 10
    
```

- $O(n)$ implementation

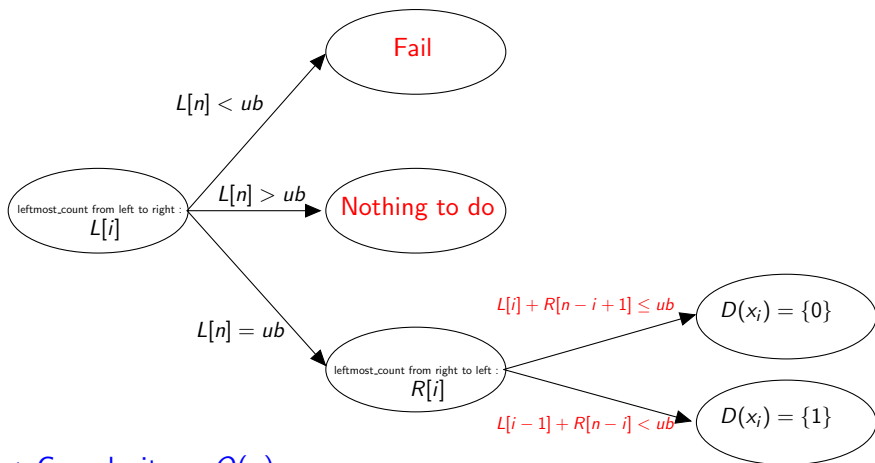


The Arc consistency algorithm

The Arc consistency algorithm



The Arc consistency algorithm



→ Complexity = $O(n)$

$AC(u = 4, q = 8, d = 12, ub = 10)$

$\mathcal{D}(x_i)$. 0 0 1 0 1

$AC(u = 4, q = 8, d = 12, ub = 10)$

$\mathcal{D}(x_i)$.	0	0	1	0	1		
$\vec{w}[i]$	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1

$AC(u = 4, q = 8, d = 12, ub = 10)$

$\mathcal{D}(x_i)$.	0	0	1	0	1		
$\vec{w}[i]$	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1
$\overleftarrow{w}[i]$	1	0	0	1	1	1	0	0	0	1	0	1	1	1	0	0	0	0	1	1	1	1

$AC(u = 4, q = 8, d = 12, ub = 10)$

$\mathcal{D}(x_i)$.	0	0	1	0	1			
$\vec{w}[i]$	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1	
$\overleftarrow{w}[i]$	1	0	0	1	1	1	0	0	0	1	0	1	1	1	0	0	0	0	1	1	1	1	
$L[i]$	0	1	1	2	3	4	4	4	4	4	4	4	5	6	7	7	7	7	8	8	9	10	10

AC($u = 4, q = 8, d = 12, ub = 10$)

$\mathcal{D}(x_i)$.	0	0	1	0	1			
$\vec{w}[i]$	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1	
$\overleftarrow{w}[i]$	1	0	0	1	1	1	0	0	0	1	0	1	1	1	0	0	0	0	1	1	1	1	
$L[i]$	0	1	1	2	3	4	4	4	4	4	4	5	6	7	7	7	7	8	8	9	10	10	
$R[n - i + 1]$	10	9	9	9	8	7	6	6	6	6	6	6	5	4	3	3	3	3	3	2	1	0	0

AC($u = 4, q = 8, d = 12, ub = 10$)

$\mathcal{D}(x_i)$.	0	0	1	0	1			
$\vec{w}[i]$	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1	
$\overleftarrow{w}[i]$	1	0	0	1	1	1	0	0	0	1	0	1	1	1	0	0	0	0	1	1	1	1	
$L[i]$	0	1	1	2	3	4	4	4	4	4	4	5	6	7	7	7	7	8	8	9	10	10	
$R[n - i + 1]$	10	9	9	9	8	7	6	6	6	6	6	6	5	4	3	3	3	3	3	2	1	0	0
$L[i] + R[n - i + 1]$	11	10	11	12	12	11	10	10	10	10	11	11	11	10	10	10	11	11	11	11	10	10	

AC($u = 4, q = 8, d = 12, ub = 10$)

$\mathcal{D}(x_i)$.	0	0	1	0	1			
$\vec{w}[i]$	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1	
$\overleftarrow{w}[i]$	1	0	0	1	1	1	0	0	0	1	0	1	1	1	0	0	0	0	1	1	1	1	
$L[i]$	0	1	1	2	3	4	4	4	4	4	4	5	6	7	7	7	7	8	8	9	10	10	
$R[n - i + 1]$	10	9	9	9	8	7	6	6	6	6	6	6	5	4	3	3	3	3	3	2	1	0	0
$L[i] + R[n - i + 1]$	11	10	11	12	12	11	10	10	10	10	10	11	11	11	10	10	10	11	11	11	11	10	
$L[i - 1] + R[n - i]$	9	10	10	10	10	10	10	10	10	10	10	9	9	9	10	10	10	10	10	9	9	10	

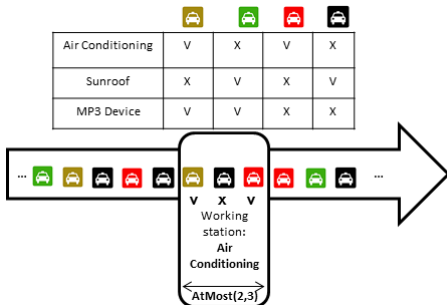
AC($u = 4, q = 8, d = 12, ub = 10$)

$\mathcal{D}(x_i)$.	0	0	1	0	1			
$\vec{w}[i]$	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1	
$\overleftarrow{w}[i]$	1	0	0	1	1	1	0	0	0	1	0	1	1	1	0	0	0	0	1	1	1	1	
$L[i]$	0	1	1	2	3	4	4	4	4	4	4	5	6	7	7	7	7	8	8	9	10	10	
$R[n - i + 1]$	10	9	9	9	8	7	6	6	6	6	6	6	5	4	3	3	3	3	3	2	1	0	0
$L[i] + R[n - i + 1]$	11	10	11	12	12	11	10	10	10	10	11	11	11	10	10	10	11	11	11	10	10	10	
$L[i - 1] + R[n - i]$	9	10	10	10	10	10	10	10	10	10	10	9	9	9	10	10	10	10	10	9	9	10	
$AC(\mathcal{D}(x_i))$	1	0	0	0	0	1	0	1	1	1	0	0	0	.	.	1	1	1	

AC($u = 4, q = 8, d = 12, ub = 10$)

$\mathcal{D}(x_i)$.	0	0	1	0	1			
$\vec{w}[i]$	1	0	1	1	1	0	0	0	0	1	0	1	1	1	0	0	0	1	0	1	1	1	
$\overleftarrow{w}[i]$	1	0	0	1	1	1	0	0	0	1	0	1	1	1	0	0	0	0	1	1	1	1	
$L[i]$	0	1	1	2	3	4	4	4	4	4	4	5	6	7	7	7	7	8	8	9	10	10	
$R[n - i + 1]$	10	9	9	9	8	7	6	6	6	6	6	6	5	4	3	3	3	3	3	2	1	0	0
$L[i] + R[n - i + 1]$	11	10	11	12	12	11	10	10	10	10	11	11	11	10	10	10	11	11	11	11	10	10	
$L[i - 1] + R[n - i]$	9	10	10	10	10	10	10	10	10	10	10	9	9	9	10	10	10	10	10	9	9	10	
$AC(\mathcal{D}(x_i))$	1	0	0	0	0	1	0	1	1	1	0	0	0	.	.	1	1	1	

Car-sequencing



Constraints

- Each class c is associated with a demand D_c .
- For each option j , each sub-sequence of size q_j must contain at most u_j cars requiring the option j .

Models

- 1 sum
- 2 gsc
- 3 amsc
- 4 amcs + gsc

Heuristics

$\langle \{lex, mid\}, \{class, opt\}, \{1, q/u, d, \delta, n - \sigma, \rho\}, \{\leq_{\Sigma}, \leq_{Euc}, \leq_{lex}\} \rangle$.
→ 34 heuristics x 5 randomized tests.

Benchmarks (CSP Lib)

- Groupe 1: 70 satisfiable instances
- Groupe 2: 4 satisfiable instances
- Groupe 3: 5 unsatisfiable instances
- Groupe 4: 7 satisfiable instances

Experimental results

Table: Experimental results : Car-sequencing

Models	G1 (70 × 34 × 5) 11900		G2 (4 × 34 × 5) 680		G3 (5 × 34 × 5) 850		G4 (7 × 34 × 5) 1190	
	#sol	time	#sol	time	#sol	time	#sol	time
sum	8480	13.93	95	76.60	0	> 1200	64	43.81
gsc	11218	3.60	325	110.99	31	276.06	140	56.61
amsc	10702	4.43	360	72.00	16	8.62	153	33.56
amsc+gsc	11243	3.43	339	106.53	32	285.43	147	66.45

Experimental results

Table: Experimental results : Car-sequencing

Models	G1 (70 × 34 × 5) 11900		G2 (4 × 34 × 5) 680		G3 (5 × 34 × 5) 850		G4 (7 × 34 × 5) 1190	
	#sol	time	#sol	time	#sol	time	#sol	time
sum	8480	13.93	95	76.60	0	> 1200	64	43.81
gsc	11218	3.60	325	110.99	31	276.06	140	56.61
amsc	10702	4.43	360	72.00	16	8.62	153	33.56
amsc+gsc	11243	3.43	339	106.53	32	285.43	147	66.45

- The level of filtering obtained by enforcing AC on the ATMOSTSEQCARD constraint is incomparable with that of the GCC encoding of the GSC constraint

Experimental results

Table: Experimental results : Car-sequencing

Models	G1 (70 × 34 × 5) 11900		G2 (4 × 34 × 5) 680		G3 (5 × 34 × 5) 850		G4 (7 × 34 × 5) 1190	
	#sol	time	#sol	time	#sol	time	#sol	time
sum	8480	13.93	95	76.60	0	> 1200	64	43.81
gsc	11218	3.60	325	110.99	31	276.06	140	56.61
amsc	10702	4.43	360	72.00	16	8.62	153	33.56
amsc+gsc	11243	3.43	339	106.53	32	285.43	147	66.45

- The level of filtering obtained by enforcing AC on the ATMOSTSEQCARD constraint is incomparable with that of the GCC encoding of the GSC constraint
- The GSC propagator seems to save more backtracks than ATMOSTSEQCARD.

Experimental results

Table: Experimental results : Car-sequencing

Models	G1 (70 × 34 × 5) 11900		G2 (4 × 34 × 5) 680		G3 (5 × 34 × 5) 850		G4 (7 × 34 × 5) 1190	
	#sol	time	#sol	time	#sol	time	#sol	time
sum	8480	13.93	95	76.60	0	> 1200	64	43.81
gsc	11218	3.60	325	110.99	31	276.06	140	56.61
amsc	10702	4.43	360	72.00	16	8.62	153	33.56
amsc+gsc	11243	3.43	339	106.53	32	285.43	147	66.45

- The level of filtering obtained by enforcing AC on the ATMOSTSEQCARD constraint is incomparable with that of the GCC encoding of the GSC constraint
- The GSC propagator seems to save more backtracks than ATMOSTSEQCARD.
- However, it's much slower than ATMOSTSEQCARD (overall a factor of **12.5** on the number of nodes explored per second!)

Crew-rostering

	Week 1							W 2	W 3	W 4	d
emp ₁	---	---	---	---	---	---	---				17
emp ₂	---	---	---	---	---	---	---	17
..	---	---	---	---	---	---	---	17
emp ₂₀	---	---	---	---	---	---	---	17
demande:	6;6;3	6;6;3	6;6;3	6;6;3	6;6;3	2;2;1	2;2;1	17*20

Constraints

- A required demand for each period.
- Each employee has to work 34 hours per week (17 shifts overall).
- Atmost 8h working shift per day.
- Atmost 5 days per week.

Models

- *sum*
- *gsc*
- *amsc*

Heuristics

- *worst employee*: $MIN(\sigma_i = n_i - \frac{21d_i}{5}), MIN(\sigma'_j = m_j - d_j^s)$.
- *worst shift*: $MIN(\sigma'_j = m_j - d_j^s), MIN(\sigma_i = n_i - \frac{21d_i}{5})$

Benchmarks

- 281 instances with different employee unavailabilities (ranging from from 18% to 46% by increment of 0.1).
- Set 1: 126 sat instances.
- Set 2: 111 instances (mostly sat).
- Set 3: 44 instances (mostly unsat).

Experimental results

Table: Experimental results: Crew-Rostering

Benchmarks	G1 ($5 \times 2 \times 126$) 1260		G2 ($5 \times 2 \times 111$) 1110		G3 ($5 \times 2 \times 44$) 440	
	#sol	time	#sol	time	#sol	time
sum	1229	12.72	574	38.45	272	5.56
gsc	1210	29.19	579	77.78	276	24.14
amsc	1237	5.82	670	31.01	284	6.22

Experimental results

Table: Experimental results: Crew-Rostering

Benchmarks	G1 ($5 \times 2 \times 126$) 1260		G2 ($5 \times 2 \times 111$) 1110		G3 ($5 \times 2 \times 44$) 440	
	#sol	time	#sol	time	#sol	time
sum	1229	12.72	574	38.45	272	5.56
gsc	1210	29.19	579	77.78	276	24.14
amsc	1237	5.82	670	31.01	284	6.22

- By analogy with the car-sequencing, there is one class with one option for each employee since we treat boolean variables.

Experimental results

Table: Experimental results: Crew-Rostering

Benchmarks	G1 ($5 \times 2 \times 126$) 1260		G2 ($5 \times 2 \times 111$) 1110		G3 ($5 \times 2 \times 44$) 440	
	#sol	time	#sol	time	#sol	time
sum	1229	12.72	574	38.45	272	5.56
gsc	1210	29.19	579	77.78	276	24.14
amsc	1237	5.82	670	31.01	284	6.22

- By analogy with the car-sequencing, there is one class with one option for each employee since we treat boolean variables.
- The GSC constraint here is equivalent to the ATMOSTSEQCARD hence can not do better than our propagator.

Experimental results

Table: Experimental results: Crew-Rostering

Benchmarks	G1 ($5 \times 2 \times 126$) 1260		G2 ($5 \times 2 \times 111$) 1110		G3 ($5 \times 2 \times 44$) 440	
	#sol	time	#sol	time	#sol	time
sum	1229	12.72	574	38.45	272	5.56
gsc	1210	29.19	579	77.78	276	24.14
amsc	1237	5.82	670	31.01	284	6.22

- By analogy with the car-sequencing, there is one class with one option for each employee since we treat boolean variables.
- The GSC constraint here is equivalent to the ATMOSTSEQCARD hence can not do better than our propagator.
- ATMOSTSEQCARD is much faster than the GSC : a factor **20.4** in terms of explored nodes per second!

Contributions

- Best existing complexity: $O(n^2)$ [Maher et al, 2008].
- A complete filtering algorithm with a linear time complexity $O(n)$.
 - Car-sequencing
 - Crew-Rostering

Future work

- Adapt the filtering rule with more general sequence constraints.
- Using the ATMOSTSEQCARD algorithm and more generally filtering algorithms in a CP-based SMT-Solver.

Thank you!

Questions?

Computing the Cardinality of Subsequences

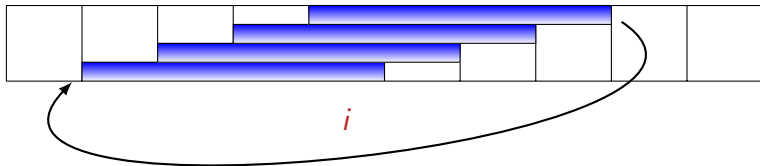
- When moving one step forward, we get *one* new subsequence (and lose another *one*)



i

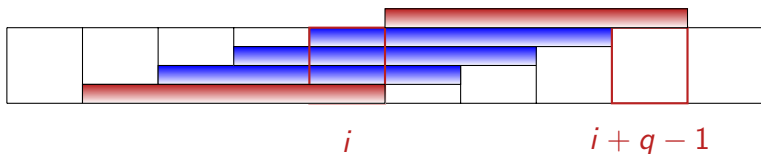
Computing the Cardinality of Subsequences

- When moving one step forward, we get *one* new subsequence (and lose another *one*)
- $i - 1 \bmod q$ points to the first subsequence at step i



Computing the Cardinality of Subsequences

- When moving one step forward, we get *one* new subsequence (and lose another *one*)
- $i - 1 \bmod q$ points to the first subsequence at step i
 - Replace $c(i - 1 \bmod q)$ by $c(i + q - 1 \bmod q) + w[i + q] - w[i]$



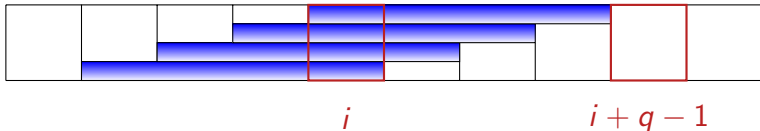
Computing the Cardinality of Subsequences

- When assigning $w[i]$ to 1, we should increment *all* subsequences
 - $O(q)$ operations



Computing the Cardinality of Subsequences

- When assigning $w[i]$ to 1, we should increment *all* subsequences
 - $O(q)$ operations
- In the previous formula: only the *negative* delta
 - $w[i + q - 1]$ is equal to the minimum value in $D(x_{i+q-1})$
 - $w[i]$ might be equal to 1 because of an assignment



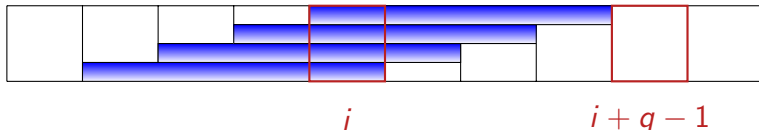
Computing the Cardinality of Subsequences

- When assigning $w[i]$ to 1, we should increment *all* subsequences
 - $O(q)$ operations
- In the previous formula: only the *negative* delta
 - $w[i + q - 1]$ is equal to the minimum value in $D(x_{i+q-1})$
 - $w[i]$ might be equal to 1 because of an assignment
- However, the positive delta is the same for all:

$$\sum_{l=1}^i (w[l] - \min(x_l))$$

- Cardinality of the j^{th} subsequence:

$$c[(i + j - 2) \bmod q] + \sum_{l=1}^i (w[l] - \min(x_l))$$

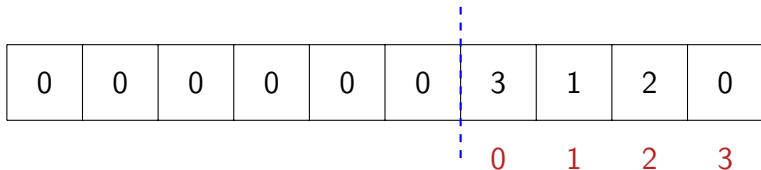


Computing the Maximum Cardinality of any Subsequence

- Computing the max, or keeping the cardinalities sorted?
 - $O(q)$ operations

Computing the Maximum Cardinality of any Subsequence

- Computing the max, or keeping the cardinalities sorted?
 - $O(q)$ operations
- We keep the *number* of subsequences of each cardinality
 - Increment all subsequences in $O(1)$



Computing the Maximum Cardinality of any Subsequence

- Computing the max, or keeping the cardinalities sorted?
 - $O(q)$ operations
- We keep the *number* of subsequences of each cardinality
 - Increment all subsequences in $O(1)$
- The maximum cardinality of any subsequence can only change by 1
 - If the number of subsequences of card $MAX(c)$ becomes 0, then $MAX(c) - 1$ is the new maximum

